

OpenAir™

# Communicative Damper Actuators KNX / PL-Link

G..B111.1E/KN





### Damper actuators 5 / 10 Nm with KNX communication

- GDB111.1E/KN with 5 Nm nominal torque
- GLB111.1E/KN with 10 Nm nominal torque
- Operating voltage AC 24 V
- Supports KNX S-Mode, LTE-Mode, and PL-Link



# Type summary

Product no.	Stock no.	Operating voltage	Positioning signal	Power consumption	Positioning time	Manual adjuster	Position feedback
GDB111.1E/KN	S55499-D190	AC 24 V	KNX-TP	1 VA / 0,5 W	450 -	V	Vaa
GLB111.1E/KN	S55499-D198	AC 24 V	KINA-1P	3 VA / 2,5 W <sup>1)</sup>	150 s	Yes	Yes
Please refer to data sheet <b>N4698</b> for information on accessories and spare parts.							

<sup>1)</sup> Actuator rotates

### Ordering (Example)

Product no.	Stock no.	Description	Amount
GDB111.1E/KN	S55499-D190	Damper Actuator KNX	1

### **Equipment combinations**

Product no.	Stock no.	Description	Doc. number / reference
ETS	Software	KNX Engineering/Commissioning Tool	www.knx.org
ABT 4.0 <sup>2)</sup>	Software	Desigo Engineering/Commissioning Tool	A6V11159913

<sup>&</sup>lt;sup>2)</sup> Release planned for April 2020

#### **Product and software versions**

Product revision	Series A
Production period	From 02/2020
Bus module FW version	4.25
ETS device profile	v1d0.knxprod

The ETS device profile can be downloaded at the following Internet address: <a href="http://siemens.com/hvac-td">http://siemens.com/hvac-td</a>

# **Product documentation**

Title	Topic	Document ID
Mounting Instruction damper actuators 5 / 10 Nm	Mounting / installation instruction for damper actuators 5 / 10 Nm without spring return	M4634
KNX bus communications	Detailed information about KNX bus communications: engineering, commissioning, addressing and settings	P3127

Related documents such as environmental declarations, CE declarations, etc., can be downloaded at the following Internet address:

http://siemens.com/bt/download

#### Safety



#### Caution

#### National safety regulations

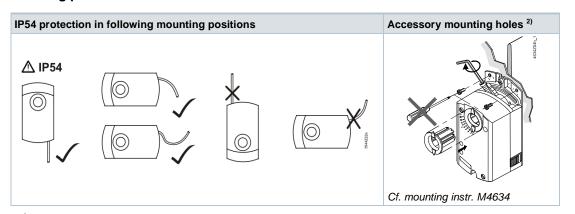
Failure to comply with national safety regulations may result in personal injury and property damage.

Observe national provisions and comply with the appropriate safety regulations.

#### **Mounting**

- Do not open the damper actuators.
- Do not use the accessory mounting holes for fixation of the damper actuators. Instead use the shaft fixation screw and the enclosed anti-rotation-bracket.

#### **Mounting positions**





Not to be used for fixation of the actuator, use anti-rotation-bracket instead.

## **Maintenance**

The damper actuators are maintenance-free.

Disconnect the electrical connections from the terminals if you want to work at the device.

#### **Disposal**



The device is considered electrical and electronic equipment for disposal in terms of the applicable European Directive and may not be disposed of as domestic garbage.

- Dispose of the device through channels provided for this purpose.
- Comply with all local and currently applicable laws and regulations.

# HMI (Human-Machine Interface)

### **Push-button operation**

Activity	Push-button operation	Confirmation
Enter / leave addressing mode	Press button <1 s	LED turns red or turns off
Reset to factory settings	Press button >20 s	LED flashes orange until device restarts
PL-Link connection test 4)	Press key >2 s and <20 s	LED flashes orange 1x

#### LED colors and patterns

Color	Pattern	Description
Off		Fault free operation or device not powered
Green	steady	Connection test successful 4)
Orange	flashing	<ul> <li>a) Factory reset in progress</li> <li>b) When a connection test was triggered: wait 4)</li> </ul>
Red	steady	<ul> <li>a) Device is in programming/addressing mode</li> <li>b) When a connection test was triggered: Connection test failed <sup>4)</sup></li> </ul>

<sup>&</sup>lt;sup>4)</sup> Function or part of the function available in PL-Link operation only

### Addressing and bus test with push button

The damper actuators can be set into addressing/programming mode by push-button:

- Press push button (>0.1 s and <1 s)</li>
- KNX bus wiring OK → LED turns red until addressing/programming is finished
- KNX bus wiring not OK → LED stays dark

## Reset with push button

The damper actuators can be reset to the OEM default values by push-button:

- Press push button > 20s
- LED flashes orange
- Device restarts

All parameters are set to factory settings.

# **Commissioning and parameterization**

The following parameters are checked or set during engineering and commissioning in the ETS engineering tool.

Parameter	Range	Description	Factory settings
Tab card "standard	,,		
Adaptive positioning	On / Off	Adaption of actual (if mechanically limited) opening range to position feedback 0100%  Off = No adaption / On = Adaption active	Off
Backup timeout	060 min 0 min = disabled	Time interval to detect communication interruption.  If disabled, the actuator drives to the last received setpoint until a new valid setpoint is received.	30 min.
Backup mode Backup position Keep last position		Actuator behavior when the communication timeout has been exceeded (no setpoint received within the defined time interval).  Backup position: Actuator drives to defined position  Keep last position: Actuator keeps position without flow control	Backup position
Backup position 0100%		Position the damper drives to in case of communication interruption	50%
Tab card "advanced	i"		
Hysteresis (COV) damper position	120%	Threshold for the damper position. COV below this value are not sent over the bus	1%
Min. repetition time damper position	10900 s	Minimum waiting time until a COV above the hysteresis threshold is sent over the bus	10 s
Minimum damper position	0100%	Electronic lower position limit	0%
Maximum damper position	0100%	Electronic upper position limit	100%
Override position 1	0100%	Damper position which can be triggered by the corresponding group object (with override priority)	0%
Override position 2	0100%	Damper position which can be triggered by the corresponding group object (with override priority)	100%

# KNX Group Objects

No.			Fla	Flags				Data poin	Data point type KNX			Range
		function	С	R	W	Т	U	ID	DPT_Name	Format	Unit	
1	Fault information	Transmit	1	1	0	1	0	219.001	_AlarmInfo	6 Byte		cf. Description below
2	Fault state	Transmit	1	1	0	1	0	1.005	_Alarm	1 bit		0 = No alarm 1 = Alarm
3	Fault transmission	Receive	1	0	1	0	1	1.003	_Enable	1 bit		0 = Disable 1 = Enable
4	Setpoint	Receive	1	1	1	0	1	5.001	_Scaling	1 Byte	%	0100%
5	Damper position	Transmit	1	1	0	1	0	5.001	_ Scaling	1 Byte	%	0100%
9	Overridden	Transmit	1	1	0	1	0	1.002	_Bool	1 bit		0 = False 1 = True
10	Override position 1	Receive	1	1	1	0	1	1.003	_Enable	1 bit		0 = Disable 1 = Enable
11	Override position 2	Receive	1	1	1	0	1	1.003	_Enable	1 bit		0 = Disable 1 = Enable
12	Opening direction	Read-only	1	1	0	0	0	1.012	_Invert	1 bit		0 = Not Inverted 1 = Inverted

#### 1 Fault information

If group object #3 "fault transmission" is set to "on", the following faults can be transmitted if they occur. In that case, group object #2 value changes to "alarm".

Error	Group obj. #1	Description	Resolution
Device jammed	XX 00 0A 03 0C 05	Target position cannot be reached due to mechanical blockage.	Remove blockage (visual inspection required). Or invert Opening direction, if it is set wrongly. Or switch on adaptive positioning, if mechanical limits are intended.
Backup mode entered	XX 01 01 02 0C 05	Actuator is in backup mode (cf. respective parameter setting)	Actuator leaves Backup mode when receiving a setpoint.
Operating hours notification	XX 01 0A 04 0C 05	Appears after a cumulated motor running time of 365 days	Check device status and control loop sensitivity

2	Fault state	Indicates whether the actuator is in fault state. If yes, read out group object #1.
3	Fault transmission	Enabling/ disabling the fault transmission. Fault transmission is disabled by default $\rightarrow$ no faults are transmitted from the actuator over the KNX bus.
4	Setpoint	Setpoint 0100% for volume flow or position, depending on the operating mode.
5	Damper position	Relative damper position $0100\%$ . An opening range less than $090^\circ$ can be normalized to $0100\%$ if adaptive positioning is set to "on".
8	Fault state	Identical with group object #2, used for compatibility reasons.
9	Overridden	Indicates whether the VAV controller is in override control either by a programming tool connected to the HMI or by objects $\#10$ / $\#11$ .
10	Override position 1	When the object is triggered, the actuator drives to the override position 1 defined by the respective ETS parameter.
11	Override position 2	When the object is triggered, the actuator drives to the override position 2 defined by the respective ETS parameter.
12	Opening direction	Opening direction of the air damper.

Power supply				
Operating voltage	GB111.1E/	AC 24 V ± 20 % (SELV) or AC 24 V class 2 (US)		
Frequency		50/60 Hz		
Power consumption	at 50 Hz			
	Actuator holds	1 VA / 0.5 W		
	Actuator rotates	3 VA / 2.5 W		
	/ lottates	o vvv z.e v		
Function data				
Positioning time for nominal rotation angle	GB111.1E/	150 s (50 Hz) 125 s (60 Hz)		
Nominal torque	GDB	5 Nm		
	GLB	10 Nm		
Maximum torque	GDB	< 7 Nm		
	GLB	< 14 Nm		
Nominal / maximum rotation angle		90° / 95° ± 2°		
Direction of rotation	Adjustable by tool or over bus	Clockwise (CW) / Counter-clockwise (CCW)		
Connection cables				
Cable length		0.9 m		
Power supply	Number of cores and cross-sectional area	2 x 0.75 mm <sup>2</sup>		
Communication	Number of cores and cross-sectional area	2 x 0.75 mm <sup>2</sup>		
Communication				
Communication protocol	Connection type	KNX-TP (galvanically isolated)		
	Bus load	5 mA		
Degree of protection				
Degree of protection	Degree of protection acc. to EN 60529 (see mounting instruction)	IP54		
Safety class	Safety class acc. to EN 60730	III		
	·			
Environmental condition	S			
Applicable standard		IEC 60721-3-x		
Operation	Climatic conditions	Class 3K5		
	Mounting location	Indoors		
	Temperature general	050 °C		
	Humidity (non condensing)	595 % r. F.		
Transport	Climatic conditions	Class 2K3		
	Temperature	-2570 °C		
	Humidity	595 % r. h.		
Storage	Climatic conditions	Class 1K3		
	Temperature	-545 °C		
	Humidity	595 % r. h.		

Directives and Standards		
Product standard	EN60730-x	
Electromagnetic compatibility (Application)	For residential, commercial and industrial environments	
	GDB111.1E/KN	GLB111.1E/KN
EU Conformity (CE)	A5W00003842 1)	A5W00000176 1)
RCM Conformity	A5W00003843 1)	A5W00000177 <sup>1)</sup>
UL, cUL AC 24 V	UL 873 http://ul.com/database	

Environmental compatibility			
The product environmental declaration A6V10209938 <sup>1)</sup> contains data on environmentally compatible product design and assessments (RoHS compliance, materials composition, packaging, environmental benefit, disposal).			

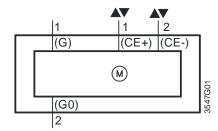
Dimensions / Weight		
Weight	Without packaging	0.6 kg
Dimensions		71 x 137 x 61 mm
Suitable drive shafts	Round shaft (with centering element)	816 mm (810 mm)
	Square shaft	612.8 mm
	Min. drive shaft length	30 mm
	Max. shaft hardness	<300 HV

<sup>1)</sup> The documents can be downloaded from <a href="http://siemens.com/bt/download">http://siemens.com/bt/download</a>

# Diagrams

### Internal diagrams

The damper actuator is supplied with two prewired cables.



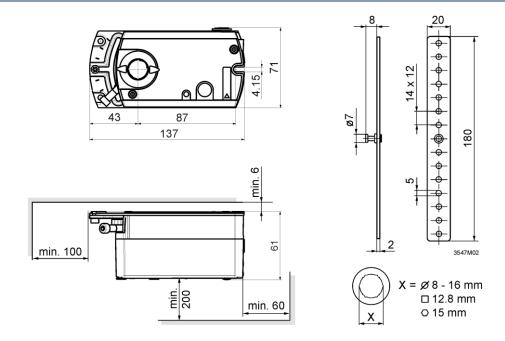
## Power supply and communication cables

Core designation	Core color	Terminal code	Description			
Cable 1: Power / black sheathing						
1	red (RD)	G	System voltage AC 24 V			
2	black (BK)	G0	System neutral AC 24 V			
Cable 2: Communication / green sheathing						
1	red (RD)	CE+	KNX CE+			
2	black (BK)	CE-	KNX CE+			

The operating voltage at terminals G and G0 must comply with the requirements under SELV or PELV.

Safety transformers with twofold insulation as per EN 61558 required; they must be designed to be on 100 % of the time.

# **Dimensions**



Measurements in mm

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