

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 8 m²
- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- · Conversion of sensor signals
- · Communication via Belimo MP-Bus





| Technical data | | |
|-----------------|--|--|
| Electrical data | Nominal voltage | AC/DC 24 V |
| Electrical data | | 50/60 Hz |
| | Nominal voltage frequency Nominal voltage range | AC 19.228.8 V / DC 21.628.8 V |
| | Power consumption in operation | 4 W |
| | Power consumption in rest position | 1.6 W |
| | Power consumption for wire sizing | 7 VA |
| | Connection supply / control | Cable 1 m, 4 x 0.75 mm ² |
| Functional data | Torque motor | 40 Nm |
| | Torque variable | 25%, 50%, 75% reduced |
| | Communicative control | MP-Bus |
| | Operating range Y | 210 V |
| | Input Impedance | 100 kΩ |
| | Options positioning signal | Open/close |
| | | 3-point (AC only) |
| | | Modulating (DC 032 V) |
| | Operating range Y variable | Start point 0.530 V |
| | Decition for all pools III | End point 2.532 V |
| | Position feedback U Position feedback U note | 210 V |
| | Position feedback U variable | Max. 0.5 mA Start point 0.58 V |
| | Position leedback o variable | End point 2.510 V |
| | Position accuracy | ±5% |
| | Direction of motion motor | selectable with switch 0/1 |
| | Direction of motion note | Y = 0 V: At switch position 0 (ccw rotation) / |
| | Birodion of motion note | 1 (cw rotation) |
| | Direction of motion variable | electronically reversible |
| | Manual override | with push-button, can be locked |
| | Angle of rotation | Max. 95° |
| | Angle of rotation note | can be limited on both sides with adjustable |
| | 3 | mechanical end stops |
| | Running time motor | 150 s / 90° |
| | Running time motor variable | 75290 s |
| | Adaptation setting range | manual |
| | Adaptation setting range variable | No action |
| | | Adaptation when switched on |
| | | Adaptation after pushing the gear |
| | | disengagement button |
| | Override control | MAX (maximum position) = 100% |
| | | MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% |
| | Override control variable | MAX = (MIN + 32%)100% |
| | Override Control Vallable | MIN = 0%(MAX - 32%) |
| | | ZS = MINMAX |
| | Sound power level, motor | 45 dB(A) |
| | Mechanical interface | Universal shaft clamp reversible 1226.7 mm |
| | Position indication | Mechanically, pluggable |
| Safety | Protection class IEC/EN | III Safety Extra-Low Voltage (SELV) |
| • | Protection class UL | UL Class 2 Supply |
| | Decree of controlling IFO/FNI | IDE 4 |

IP54

Degree of protection IEC/EN

Rotary actuator, modulating, communicative, AC/ DC 24 V, 40 Nm, Communication via Belimo MP-Bus



Technical data

| ^ - | | |
|------------|--|--|
| | | |
| | | |

| Degree of protection NEMA/UL | NEMA 2 |
|--|---|
| Enclosure | UL Enclosure Type 2 |
| EMC | CE according to 2014/30/EU |
| Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| Certification UL | cULus according to UL60730-1A, UL60730-2- 14 and CAN/CSA E60730-1:02 |
| Certification UL note | The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
| Mode of operation | Type 1 |
| Rated impulse voltage supply / control | 0.8 kV |
| Control pollution degree | 3 |
| Ambient temperature | -3050°C |
| Storage temperature | -4080°C |
| Ambient humidity | Max. 95% r.H., non-condensing |
| Servicing | maintenance-free |
| Weight | 1.8 kg |

Safety notes



Weight

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation
 or aggressive gases interfere directly with the actuator and that is ensured that the
 ambient conditions remain at any time within the thresholds according to the data
 sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed
 of as household refuse. All locally valid regulations and requirements must be
 observed.

Product features

Mode of operation

Conventional operation:

The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0.5...100% and as slave control signal for other actuators.

Operation on Bus:

The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.



Product features

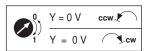
High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.



Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).

Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

| | Description | Туре |
|------------------------|---|------------|
| Gateways | Gateway MP to Modbus RTU | UK24MOD |
| | Gateway MP zu BACnet MS/TP | UK24BAC |
| | Gateway MP to LonWorks | UK24LON |
| | Gateway MP to KNX | UK24EIB |
| | Description | Туре |
| Electrical accessories | Auxiliary switch 1 x SPDT add-on | S1A |
| | Auxiliary switch 2 x SPDT add-on | S2A |
| | Auxiliary switch 2 x SPDT add-on, grau | S2A/300 GR |
| | Auxiliary switch 2 x SPDT add-on, grau | S2A/500 GR |
| | Feedback potentiometer 140 Ω add-on | P140A |
| | Feedback potentiometer 140 Ω add-on, grau | P140A GR |
| | Feedback potentiometer 200 Ω add-on | P200A |
| | Feedback potentiometer 500 Ω add-on | P500A |
| | Feedback potentiometer 500 Ω add-on, grau | P500A GR |
| | Feedback potentiometer 1 k Ω add-on | P1000A |
| | Feedback potentiometer 1 kΩ add-on, grau | P1000A GR |
| | Feedback potentiometer 2.8 k Ω add-on | P2800A |
| | Feedback potentiometer 2.8 k Ω add-on, grau | P2800A GR |
| | Feedback potentiometer 5 k Ω add-on | P5000A |
| | Feedback potentiometer 5 k Ω add-on, grau | P5000A GR |
| | Feedback potentiometer 10 k Ω add-on | P10000A |
| | Feedback potentiometer 10 kΩ add-on, grau | P10000A GR |
| | Positioner for wall mounting | CRP24-B1 |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device | ZK1-GEN |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
| | Connecting board MP-Bus for wiring boxes EXT-WR-FPMP | ZFP2-MP |
| | MP-Bus power supply for MP actuators | ZN230-24MP |
| | Description | Туре |
| Mechanical accessories | Actuator arm for standard shaft clamp | AH-GMA |
| | Ball joint suitable for damper crank arm KH8 / KH10 | KG10A |
| | Damper crank arm Slot width 8.2 mm, clamping range Ø1425 mm | KH10 |
| | Anti-rotation mechanism 230 mm, Multipack 20 pcs. | Z-ARS230 |
| | Mounting kit for linkage operation for flat installation | ZG-GMA |
| | | |



Accessories

| | Description | Туре |
|---------------|--|--------|
| | Base plate extension for GMA to GM, Multipack 20 pcs. | Z-GMA |
| | Position indicator, Multipack 20 pcs. | Z-PI |
| | Description | Туре |
| Service Tools | Service Tool, with ZIP-USB function | ZTH EU |
| OCIVICE TOOIS | Service 100i, With Zir -00b function | ZIIILU |
| OCTAIGG 10013 | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |

Electrical installation

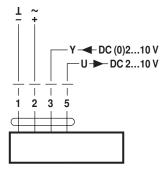


Notes

- · Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams

AC/DC 24 V, modulating



Cable colours:

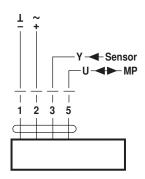
1 = black

2 = red

3 = white

5 = orange

Operation on the MP-Bus



Cable colours:

1 = black

2 = red

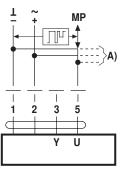
3 = white

5 = orange

Functions

Functions when operated on MP-Bus

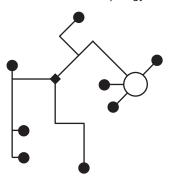
Connection on the MP-Bus



A) more actuators and sensors

(max.8)

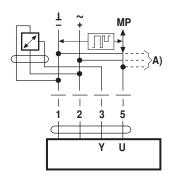
MP-Bus Network topology



There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable

- · no shielding or twisting necessary
- no terminating resistors required

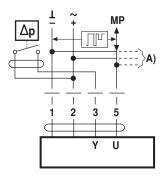
Connection of external switching contact



Connection of active sensors

A) more actuators and sensors (max.8)

- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV



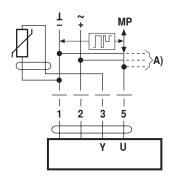
A) more actuators and sensors

- Switching current 16 mA @ 24 V
- · Start point of the operating range must be parameterised on the MP actuator as ≥ 0.5 V



Functions

Connection of passive sensors

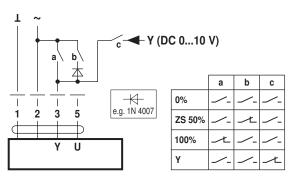


| Ni1000 | –28+98°C | 8501600 Ω ²⁾ |
|--------|--------------|--------------------------|
| PT1000 | −35+155°C | 8501600 Ω ²⁾ |
| NTC | -10+160°C 1) | 200 Ω60 kΩ ²⁾ |

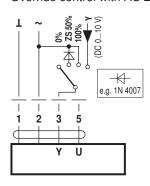
- A) more actuators and sensors (max.8)
- 1) Depending on the type
- 2) Resolution 1 Ohm

Functions with basic values (conventional mode)

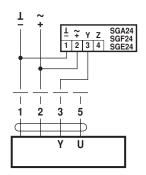
Override control with AC 24 V with relay contacts

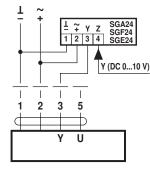


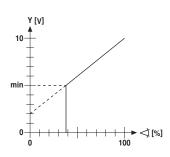
Override control with AC 24 V with rotary switch



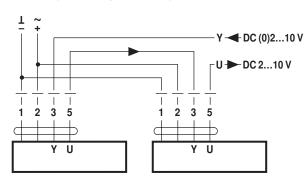
Control remotely 0...100% with Minimum limit with positioner SG.. positioner SG..

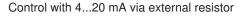


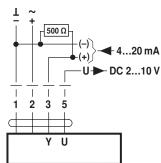




Follow-up control (position-dependent)







Caution:

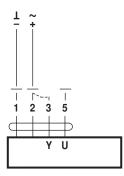
The operating range must be set to DC 2...10 V.

The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V



Functions

Functional check



Procedure

- 1. Connect 24V to connections 1
- and 2
- 2. Disconnect connection 3:
- with direction of rotation 0:

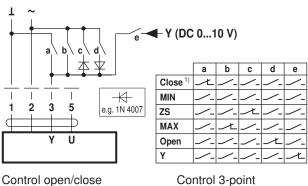
Actuator rotates to the left

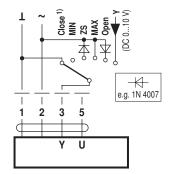
- with direction of rotation 1:
- Actuator rotates to the right
- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts

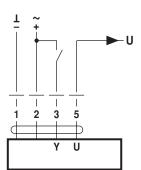
Override control and limiting with AC 24 V with rotary switch

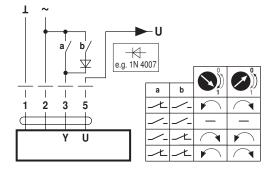




1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

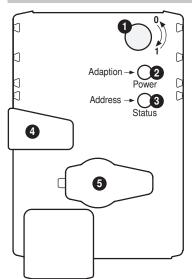
Control open/close







Operating controls and indicators



Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfuntion

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

Flickering: MP communication active

On: Adaptation or synchronising process active Flashing: Request for addressing from MP master Press button: Confirmation of the addressing

4 Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible Release button: Gear engages, synchronisation starts, followed by standard mode

5 Service plug

For connecting parameterisation and service tools

Check power supply connection

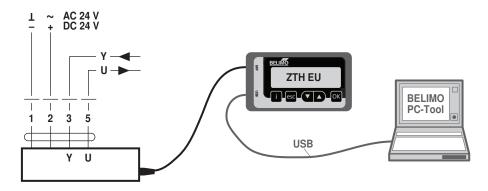
2 Off and 3 On Possible wiring error in power supply

Service

Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



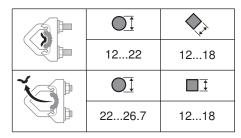


Dimensions [mm]

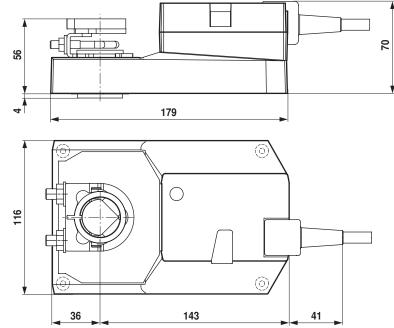
Spindle length



Clamping range



Dimensional drawings



Further documentation

- · Overview MP Cooperation Partners
- · Tool connections
- Introduction to MP-Bus Technology