

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 1 m²
- Torque motor 5 Nm
- Nominal voltage AC/DC 24 V
- Control communicative
- Communication via BACnet MS/TP or Modbus RTU

Technical data sheet



LM24A-MOD-J6



Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
|-----------------|--|---|
| Liccuitai data | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.228.8 V / DC 21.628.8 V |
| | Power consumption in operation | 2.5 W |
| | Power consumption in rest position | 1.3 W |
| | Power consumption for wire sizing | 5 VA |
| | Connection supply / control | Connector socket RJ12 |
| | | <u> </u> |
| Functional data | Torque motor | 5 Nm |
| | Torque variable | 25%, 50%, 75% reduced |
| | Communicative control | BACnet MS/TP |
| | <u></u> | Modbus RTU (default setting) |
| | Direction of motion motor | selectable with switch 0/1 |
| | Direction of motion note | Y = 0%: At switch position 0 (ccw rotation) / 1 (cw rotation) |
| | Direction of motion variable | electronically reversible |
| | Manual override | with push-button, can be locked |
| | Angle of rotation | Max. 95° |
| | Angle of rotation note | can be limited on both sides with adjustable |
| | Angle of foldulon note | mechanical end stops |
| | Running time motor | 150 s / 90° |
| | Running time motor variable | 35150 s |
| | Adaptation setting range | manual |
| | Adaptation setting range variable | No action |
| | | Adaptation when switched on |
| | | Adaptation after pushing the gear disengagement |
| | | button |
| | Override control, controllable via bus communication | MAX (maximum position) = 100% MIN (minimum position) = 0% |
| | Communication | ZS (intermediate position) = 50% |
| | Override control variable | MAX = (MIN + 32%)100% |
| | | MIN = 0%(MAX – 32%) |
| | | ZS = MINMAX |
| | Sound power level, motor | 35 dB(A) |
| | Mechanical interface | Universal shaft clamp 620 mm |
| | Position indication | Mechanically, pluggable |
| Safety data | Protection class IEC/EN | III Safety Extra-Low Voltage (SELV) |
| | Protection class UL | UL Class 2 Supply |
| | Degree of protection IEC/EN | IP54 |
| | Degree of protection NEMA/UL | NEMA 2 |
| | Enclosure | UL Enclosure Type 2 |
| | EMC | CE according to 2014/30/EU |



| Technical data sheet | LM24A-MOD-J6 | |
|--|---|--|
| Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 | |
| Certification UL | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02 | |
| Certification UL note | The UL marking on the actuator depends on the production site, the device is UL-compliant in any case | |
| Mode of operation | Type 1 | |
| Rated impulse voltage supply / control | 0.8 kV | |
| Control pollution degree | 3 | |
| Ambient temperature | -3050°C | |
| Storage temperature | -4080°C | |
| Ambient humidity | Max. 95% r.H., non-condensing | |
| Servicing | maintenance-free | |
| Weight | 0.65 kg | |

Safety notes



Weight

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases
 interfere directly with the device and that it is ensured that the ambient conditions remain within the
 thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning
 the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

The actuator is fitted with an integrated interface for BACnet MS/TP and Modbus RTU, it receives the digital positioning signal from the control system and returns the current status.

Configurable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

The communication parameters of the bus systems (address, baud rate etc.) are set with the ZTH EU. Pressing the "Address" button on the actuator while connecting the supply voltage, resets the communication parameters to the factory setting.

Quick addressing: The BACnet and Modbus address can alternatively be set using the buttons on the actuator and selecting 1...16. The value selected is added to the «Basic address» parameter and results in the effective BACnet and Modbus address.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

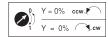
The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.





Adaptation and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).

Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

| Electrical accessories | Description | Туре |
|------------------------|---|------------|
| | Feedback potentiometer 10 kΩ add-on | P10000A |
| | Feedback potentiometer 1 kΩ add-on | P1000A |
| | Feedback potentiometer 140 Ω add-on | P140A |
| | Feedback potentiometer 200 Ω add-on | P200A |
| | Feedback potentiometer 2.8 kΩ add-on | P2800A |
| | Feedback potentiometer 5 kΩ add-on | P5000A |
| | Feedback potentiometer 500 Ω add-on | P500A |
| | Auxiliary switch 1 x SPDT add-on | S1A |
| | Auxiliary switch 2 x SPDT add-on | S2A |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket | ZK1-GEN |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
| Mechanical accessories | Description | Туре |
| | Shaft extension 170 mm Ø10 mm for damper shaft Ø 616 mm | AV6-20 |
| | Shaft clamp one-sided, clamping range Ø620 mm, Multipack 20 pcs. | K-ELA |
| | Shaft clamp one-sided, clamping range Ø610 mm, Multipack 20 pcs. | K-ELA10 |
| | Shaft clamp one-sided, clamping range Ø613 mm, Multipack 20 pcs. | K-ELA13 |
| | Shaft clamp one-sided, clamping range Ø616 mm, Multipack 20 pcs. | K-ELA16 |
| | Anti-rotation mechanism 180 mm, Multipack 20 pcs. | Z-ARS180 |
| | Position indicator, Multipack 20 pcs. | Z-PI |
| | Grommet for RJ connection module, 50 pcs. | Z-STRJ.1 |
| | Form fit insert 10x10 mm, Multipack 20 pcs. | ZF10-LMA |
| | Form fit insert 12x12 mm, Multipack 20 pcs. | ZF12-LMA |
| | Form fit insert 8x8 mm, Multipack 20 pcs. | ZF8-LMA |
| | Form fit insert 10x10 mm, with angle of rotation limiter and position indication, Multipack 20 pcs. | ZFRL10-LMA |
| | Form fit insert 12x12 mm, with angle of rotation limiter and position indication, Multipack 20 pcs. | ZFRL12-LMA |
| | Form fit insert 8x8 mm, with angle of rotation limiter and position indication, Multipack 20 pcs. | ZFRL8-LMA |
| Service tools | Description | Туре |
| | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
| | Service Tool, with ZIP-USB function, for configurable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH EU |

Electrical installation



Always fit feed pins in pairs!

Only attach and remove connection cable when de-energised!

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

Maximum cable length for star wiring <5 m.

Maximum baud rate for star wiring 38'400 Bd.



Wiring diagrams

RJ12 socket

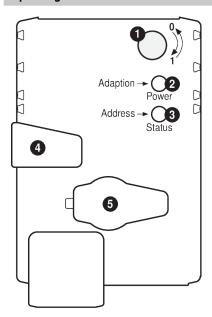


1 AC/DC 24 V 2 GND 3 D- (A) 4 D+ (B)

Modbus signal assignment:

5 AC/DC 24 V C1 = D- = A 6 GND C2 = D+ = B

Operating controls and indicators



1 Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfuntion

On: In operation

Flashing: In address mode: Pulses according to set address (1...16)

When starting: Reset to factory setting (Communication)

Press button: In standard mode: Triggers angle of rotation adaptation

In address mode: Confirmation of set address (1...16)

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronising process active

or actuator in address mode (LED display green flashing)

Flickering: BACnet / Modbus communication active

Press button: In operation (>3 s): Switch address mode on and off

In address mode: Address setting by pressing several times When starting (>5 s): Reset to factory setting (Communication)

4 Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible

Release button: Gear engages, synchronisation starts, followed by standard mode

5 Service plug

For connecting parameterisation and service tools

Check power supply connection

2 Off and 3 On Possible wiring error in power supply

Service

Quick addressing

- 1. Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address.
- 2. Set the address by pressing the "Address" button the corresponding number of times (1...16).
- 3. The green LED flashes in accordance with the address that has been entered (...16). If the address is not correct, then this can be reset in accordance with Step 2.
- 4. Confirm the address setting by pressing the green "Adaption" button.

If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded.

The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket.

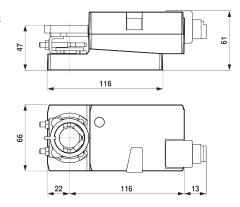
For an extended parametrisation the PC tool can be connected.





Dimensions

Dimensional drawings



Clamping range

| <u> </u> | | $\Diamond $ |
|----------|---------|-------------|
| 620 | ≥6 | ≤20 |

Shaft length



Min. 37

Further documentation

- Tool connections
- Description Protocol Implementation Conformance Statement PICS
- Description Modbus register

Application notes

• For digital control of actuators in VAV applications patent EP 3163399 must be considered.