Configurable damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. $0.8 \mathrm{~m}^{2}$
- Torque motor 4 Nm
- Nominal voltage AC/DC 24 V
- Control modulating $2 . . .10 \mathrm{~V}$ variable
- Position feedback 2... 10 V variable
- Running time motor 2.5 s variable


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 13 W |
|  | Power consumption in rest position | 2 W |
|  | Power consumption for wire sizing | 23 VA |
|  | Power consumption for wire sizing note | Imax 20 A @ 5 ms |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 4 Nm |
|  | Torque variable | 25\%, $50 \%$, $75 \%$ reduced |
|  | Operating range Y | 2...10 V |
|  | Input Impedance | $100 \mathrm{k} \Omega$ |
|  | Options positioning signal | Open/close |
|  |  | Modulating (DC 0... 32 V ) |
|  | Operating range Y variable | Start point 0.5... 30 V <br> End point 2.5... 32 V |
|  | Position feedback U | 2... 10 V |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point $0.5 . . .8 \mathrm{~V}$ <br> End point 2.5... 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | selectable with switch 0/1 |
|  | Direction of motion note | $\mathrm{Y}=0 \mathrm{~V}$ : At switch position 0 (ccw rotation) / <br> 1 (cw rotation) |
|  | Direction of motion variable | electronically reversible |
|  | Manual override | with push-button, can be locked |
|  | Angle of rotation | Max. $95^{\circ}$ |
|  | Angle of rotation note | can be limited on both sides with adjustable mechanical end stops |
|  | Minimum angle of rotation | Min. $30^{\circ}$ |
|  | Running time motor | $2.5 \mathrm{~s} / 90^{\circ}$ |
|  | Running time motor variable | 2.5... 10 s |
|  | Adaptation setting range | manual (automatic on first power-up) |
|  | Adaptation setting range variable | No action |
|  |  | Adaptation when switched on |
|  |  | Adaptation after pushing the gear disengagement button |
|  | Override control | $\begin{aligned} & \text { MAX (maximum position) }=100 \% \\ & \text { MIN (minimum position) }=0 \% \\ & \text { ZS (intermediate position, AC only) }=50 \% \end{aligned}$ |
|  | Override control variable | MAX $=(\mathrm{MIN}+32 \%) . . .100 \%$ |
|  |  | MIN = 0\% ...(MAX - 32\%) |
|  |  | ZS = MIN...MAX |
|  | Sound power level, motor | $54 \mathrm{~dB}(\mathrm{~A})$ |
|  | Mechanical interface | Universal shaft clamp 8...26.7 mm |
|  | Position indication | Mechanically, pluggable |
| Safety | Protection class IEC/EN | III Safety Extra-Low Voltage (SELV) |
|  | Protection class UL | UL Class 2 Supply |


| Safety | Degree of protection IEC/EN | IP54 |
| :---: | :---: | :---: |
|  | Degree of protection NEMA/UL | NEMA 2 |
|  | Enclosure | UL Enclosure Type 2 |
|  | EMC | CE according to 2014/30/EU |
|  | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
|  | Certification UL | cULus according to UL60730-1A, UL60730-214 and CAN/CSA E60730-1:02 |
|  | Certification UL note | The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
|  | Mode of operation | Type 1 |
|  | Rated impulse voltage supply / control | 0.8 kV |
|  | Control pollution degree | 3 |
|  | Ambient temperature | $-30 . .40^{\circ} \mathrm{C}$ |
|  | Ambient temperature note | Caution: $+40 \ldots+50^{\circ} \mathrm{C}$ utilisation possible only under certain restrictions. Please contact your supplier. |
|  | Storage temperature | $-40 \ldots 80^{\circ} \mathrm{C}$ |
|  | Ambient humidity | Max. 95\% r.H., non-condensing |
|  | Servicing | maintenance-free |
| Weight | Weight | 0.99 kg |

## Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

Mode of operation The actuator is connected with a standard modulating signal of $0 . . .10 \mathrm{~V}$ and drives to the position defined by the positioning signal. Measuring voltage $U$ serves for the electrical display of the damper position $0.5 \ldots 100 \%$ and as slave control signal for other actuators.

## Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
Manual override Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation
Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of $30^{\circ}$ must be allowed for.

High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.
The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics.
The actuator then moves into the position defined by the positioning signal.


## Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position ( $0 \%$ ).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## Accessories



## Accessories

|  | Description | Type |
| :---: | :---: | :---: |
|  | Shaft clamp one-sided, clamping range Ø8... 26 mm with insert, Multipack 20 pcs. | K-ENMA |
|  | Shaft clamp one-sided, clamping range $\varnothing 8 . . .26 \mathrm{~mm}$, Multipack 20 pcs. | K-ENSA |
|  | Shaft clamp reversible, clamping range $\varnothing 8 . . .20 \mathrm{~mm}$, Multipack 20 pcs . | K-NA |
|  | Form fit insert $8 \times 8 \mathrm{~mm}$, Multipack 20 pcs . | ZF8-NMA |
|  | Form fit insert $10 \times 10 \mathrm{~mm}$, Multipack 20 pcs . | ZF10-NSA |
|  | Form fit insert $12 \times 12 \mathrm{~mm}$, Multipack 20 pcs . | ZF12-NSA |
|  | Form fit insert $15 \times 15 \mathrm{~mm}$, Multipack 20 pcs . | ZF15-NSA |
|  | Form fit insert $16 \times 16 \mathrm{~mm}$, Multipack 20 pcs . | ZF16-NSA |
|  | Mounting kit for linkage operation for flat installation | ZG-NMA |
|  | Anti-rotation mechanism 180 mm , Multipack 20 pcs. | Z-ARS180 |
|  | Base plate extension for NM..A to NM.., Multipack 20 pcs. | Z-NMA |
|  | Position indicator, Multipack 20 pcs. | Z-PI |
|  | Description | Type |
| Service Tools | Service Tool, with ZIP-USB function | ZTH EU |
|  | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
|  | Adapter for Service-Tool ZTH | MFT-C |
|  | * Adapter Z-SPA <br> It is imperative that this adapter will be ordered if an auxiliary switch or a feed is required and if at the same time the shaft clamp is installed on the rear sid with short-axis installation). | dback potentiometer e of the actuator (e.g. |

## Electrical installation

Notes $\quad$ - Connection via safety isolating transformer.

## Wiring diagrams

AC/DC 24 V , modulating


## Cable colours:

1 = black
2 = red
3 = white
5 = orange
Signal cable lengths


## A = Actuator

$\mathrm{C}=$ Control unit (controlling unit)
$\mathrm{L} 1=$ Connecting cable of the actuator
L2 = Customer cable
Ltot $=$ Maximum signal cable length

## Note:

When several actuators are connected in parallel, the maximum signal cable length must be divided by the number of actuators.

## Electrical installation



A = Actuator
$\mathrm{C}=$ Control unit (controlling unit) L1 = Connecting cable of the actuator

## Note:

There are no special restrictions on installation if the supply and the data cable are routed separately.

## Functions

Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts


Override control with AC 24 V with rotary switch


Control remotely $0 . . .100 \%$ with Minimum limit with positioner SG.. positioner SG..


Follow-up control (position-dependent)



Control with $4 . . .20 \mathrm{~mA}$ via external resistor


## Caution:

The operating range must be set to DC 2... 10 V .
The $500 \Omega$ resistor converts the 4... 20 mA current signal to a voltage signal DC 2... 10 V

## Functions

Functional check


## Procedure

1. Connect 24 V to connections 1
and 2
2. Disconnect connection 3:

- with direction of rotation 0 :

Actuator rotates to the left

- with direction of rotation 1 :

Actuator rotates to the right
3. Short-circuit connections 2 and 3:

- Actuator runs in opposite direction


## Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts


Control open/close


Override control and limiting with AC 24 V with rotary switch


1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V .

Operating controls and indicators

(1) Direction of rotation switch

Switch over: Direction of rotation changes
(2) Push-button and LED display green

Off: $\quad$ No power supply or malfuntion
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode
(3) Push-button and LED display yellow

Off: Standard mode
On: $\quad$ Adaptation or synchronising process active
Press button: No function
(4) Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronisation starts, followed by standard mode
(5) Service plug

For connecting parameterisation and service tools
Check power supply connection
(2) Off and (3) On Possible wiring error in power supply

## Installation notes

$$
\begin{array}{ll}
\text { Negative torque } \begin{array}{l}
\text { Max. } 50 \% \text { of the torque (Caution: Application possible only with restrictions. Please } \\
\text { contact your supplier.) }
\end{array}
\end{array}
$$

## Service

Service Tools connection
The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.
Connection ZTH EU / PC-Tool


## Dimensions [mm]

Spindle length


Clamping range

*Option: Shaft clamp mounted below (accessories K-NA needed)
*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.

## Dimensional drawings



