

Technical data sheet

LR24A-MOD

Communicative rotary actuator for ball valves

- Torque motor 5 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- Conversion of sensor signals
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control



WP27BUS

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	2.5 W
	Power consumption in rest position	1.3 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m, 6 x 0.75 mm ²
Functional data	Torque motor	5 Nm
	Communicative control	BACnet MS/TP
		Modbus RTU (ex works)
		MP-Bus
	Operating range Y	210 V
	Operating range Y variable	0.510 V
	Position feedback U	210 V
	Position feedback U note	Max. 1 mA
	Position feedback U variable	Start point 0.58 V
		End point 210 V
	Position accuracy	±5%
	Manual override	with push-button, can be locked
	Running time motor	90 s / 90°
	Running time motor variable	35420 s
	Adaptation setting range	manual (automatic on first power-up)
	Adaptation setting range variable	No action
		Adaptation when switched on
		Adaptation after pushing the gear disengagement button
	Override control, controllable via bus	MAX (maximum position) = 100%
	communication	MIN (minimum position) = 0%
	commented for	ZS (intermediate position) = 50%
	Override control variable	MAX = (MIN + 33%)100%
		MIN = 0%(MAX - 33%)
		ZS = MINMAX
	Sound power level, motor	35 dB(A)
	Position indication	Mechanically, pluggable
Safety	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
-	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2- 14 and CAN/CSA E60730-1:02
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
		<u> </u>

LR24A-MOD

Rotary actuator, modulating, communicative, hybrid, AC/ DC 24 V, 5 Nm $\,$

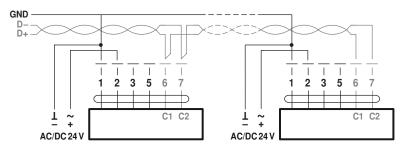


Technical data			
Safety	Ambient temperature	-3050°C	
-	Storage temperature	-4080°C	
	Ambient humidity	Max. 95% r.H., non-condensing	
	Servicing	maintenance-free	
Weight	Weight	0.52 kg	
weight	weight	0.52 kg	
Safety notes			
$\underline{\wedge}$	 This device has been designed for use in stationary heating, ventilation and air- conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport. 		
	or aggressive gases interfere direc	in case that no (sea) water, snow, ice, insolation tly with the actuator and that is ensured that the ime within the thresholds according to the data	
		rry out installation. All applicable legal or must be complied during installation.	
		on of rotation may only be operated by authorised n must not in particular be reversed in a frost	
	 The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user. 		
	Cables must not be removed from the device.		
		electronic components and must not be disposed valid regulations and requirements must be	
Product features			
Mode of operation	The actuator is fitted with an integrated interface for BACnet MS/TP, Modbus RTU and MP-Bus. It receives the digital positioning signal from the control system and returns the current status.		
Converter for sensors		ive, active or with switching contact). In this way, asily digitised and transferred to the bus systems :	
Parametrisable actuators	modified with the Belimo Service Toc The communication parameters of th with the ZTH EU. Pressing the "Addre supply voltage, resets the communica Quick addressing: The BACnet and M buttons on the actuator and selecting	common applications. Single parameters can be ols MFT-P or ZTH EU. e bus systems (address, baud rate etc.) are set ess" button on the actuator while connecting the ation parameters to the factory setting. Modbus address can alternatively be set using the 1 16. The value selected is added to the «Basic e effective BACnet and Modbus address.	
Combination analogue - communicative (hybrid mode)	With conventional control by means of Modbus can be used for the commun	of an analogue positioning signal, BACnet or nicative position feedback	
Simple direct mounting		e ball valve with only one central screw. The g-in position indication. The mounting orientation lected in 90° steps.	
Manual override	Manual override with push-button po- button is pressed or remains locked).	ssible (the gear is disengaged for as long as the	
Adjustable angle of rotation	Adjustable angle of rotation with mec	hanical end stops.	
High functional reliability		equires no limit switches and automatically stops	
Home position	the actuator carries out an adaption, feedback adjust themselves to the m	sition defined by the positioning signal.	

LR24A-MOD	Rotary actuator, modulating, communicative, hybrid, AC/ DC 24 V, 5 Nm	BELIMO			
Product features					
Adaption and synchronisation	An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)				
Accessories					
	Description	Туре			
Electrical accessories	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device	ZK1-GEN			
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN			
	Description	Туре			
Service Tools	Service Tool, Setting tool with ZIP-USB function	ZTH EU			
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P			
	Adapter for Service-Tool ZTH	MFT-C			
Electrical installation					
Notes	 Connection via safety isolating transformer. The wiring of the line for BACnet MS/TP / Modbus RTU is to be accordance with applicable RS485 regulations. 				

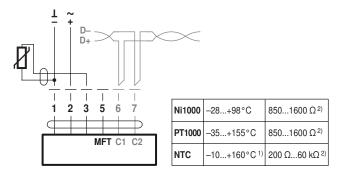
Wiring diagrams

BACnet MS/TP / Modbus RTU



٠

Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Cable colours: 1 = black 2 = red 3 = white 5 = orange 6 = pink 7 = grey BACnet / Modbus signal assignment: C1 = D - = AC2 = D + = B

1) depending on type
 2) Resolution 1 Ohm

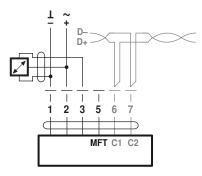
Modbus / BACnet: Supply and communication are not galvanically isolated.

Connect earth signal of the devices with one another.



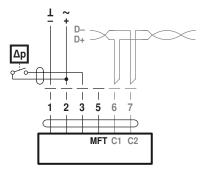
Electrical installation

Connection with active sensor, e.g. 0...10 V @ 0...50°C

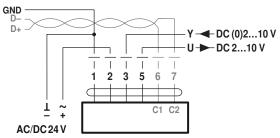


Possible voltage range: 0...32 V (resolution 30 mV)

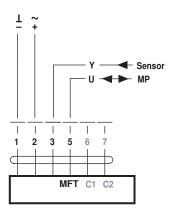
Connection with switching contact, e.g. Δp monitor



Modbus RTU / BACnet MS/TP with analogue setpoint (hybrid mode) $% \left(A_{1}^{2}\right) =0$



Operation on the MP-Bus



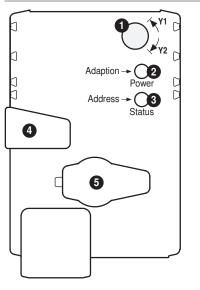
Requirements for switching contact: The switching contact must be able to accurately switch a current of 16 mA @ 24 V.

LR24A-MOD

Service



Operating controls and indicators



	1 Direction of rotat				
	Switch over:	Direction of rotation changes			
	Push-button and Off: On: Flashing: Press button:	LED display green No power supply or malfuntion In operation In address mode: Pulses according to set address (116) When starting: Reset to factory setting (Communication) In standard mode: Triggers angle of rotation adaptation In address mode: Confirmation of set address (116)			
	 Push-button and Off: On: Flickering: Press button: 	LED display yellow Standard mode Adaptation or synchronising process active or actuator in address mode (LED display green flashing) BACnet / Modbus communication active In operation (>3 s): Switch address mode on and off In address mode: Address setting by pressing several times When starting (>5 s): Reset to factory setting (Communication)			
	 Gear disengagen Press button: Release button: Service plug For connecting pa 	nent button Gear disengages, motor stops, manual override possible Gear engages, synchronisation starts, followed by standard mode rameterisation and service tools			
	Check power supply	Check power supply connection			
	2 Off and 3 On	Possible wiring error in power supply			
1	 Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address. Set the address by pressing the "Address" button the corresponding number of times (116). The green LED flashes in accordance with the address that has been entered (16). If the address is not correct, then this can be reset in accordance with Step 2. Confirm the address setting by pressing the green "Adaption" button. If no confirmation occurs for 60 seconds, then the address procedure is ended. Any 				

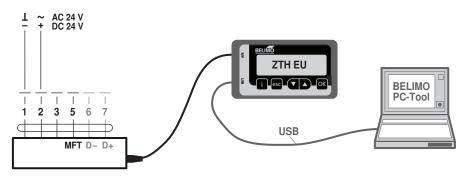
If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded.

The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

Service Tools connection

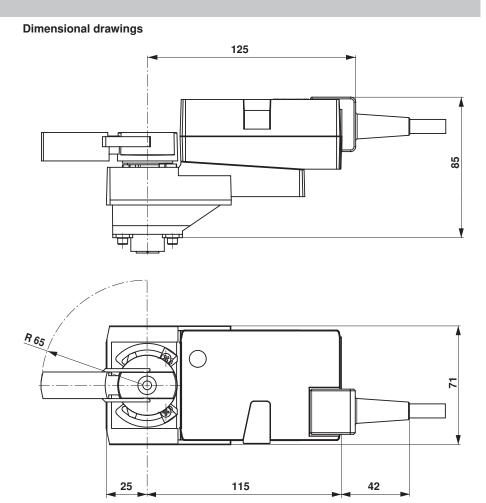
Quick adressing

ction The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.





Dimensions [mm]



Further documentation

- Tool connections
- Description Protocol Implementation Conformance Statement PICS •
 - . Description Modbus register
 - Overview MP Cooperation Partners
 - MP Glossary .
 - •
- Introduction to MP-Bus Technology The complete product range for water applications .
- . Data sheets for ball valves
- Installation instructions for actuators and/or ball valves •
- · General notes for project planning