# Compact actuator with electronic emergency return for PICVs and globe valves 



| MODEL | CONTROL | POWER <br> SUPPLY | FORCE <br> [N] | IP |
| :---: | :---: | :---: | :---: | :---: |
| MVC503R-MB | Modbus | $24 \mathrm{Vac} / \mathrm{dc}$ | 300 | 54 |

## APPLICATION AND USE

MVC503R-MB actuator with fail safe function can be used with valves push/pull (using auto stroke calibration mode) or with valves with spring using fixed stroke mode. The main application is to control hot/cool water flow rate in two/four pipes terminal units, zone, small reheating and dehumidifcation coils. Fail safe function is used in all the applications where we need to specify the valve position (fully open or fully closed) in case of power failure.
The Modbus control is perfect for systems with large numbers of control valves where the number of I/O points of the BMS can be drastically reduced using a field bus.
MVC503R-MB is equipped with MODBUS (SLAVE) communication protocol enabling the communication with other MODBUS devices (MASTER).

## OPERATION

MVC503R-MB is an electrical bidirectional actuator. The valve stem is activated through a stepper motor and a gear train optimised in order to have high performances and minimal noise emissions.
The actuator is equipped with super capacitors able to provide the energy to fully close or fully open the valve in case of power loss. The final position of the actuator can be selected via Modbus configuration.
The actuator is equipped with a mechanism able to stop the motor when the force of 300 N is reached. If auto stroke calibration is set, the software enables the stroke calibration, so it can be used on any valve, as long as it respects the maximum stroke limit allowed ( 12 mm max).
MVC503R-MB is a modulating actuator and it can be controlled through Modbus connection directly from the BMS without the need of a voltage or current control signal. The actuator is also equipped with 5 LEDs whose operation is explained in the table at page 5.

## VALVE \& ACTUATOR COMPATIBILITY

MVC503R-MB is used with CONTROLLI valves without spring. The actuator has a joint that allows a solid connection to the valve stem. MVC503R-MB can also be used with CONTROLLI valves with spring. In this case the actuator is not solidly connected to the valve stem, but pushes the stem downwards during movement; the return of the stem is done by the spring on the valve itself which guarantees the contact of the stem with the actuator.
In case of use of non Controlli valves please contact technical secretariat for proper adaptor.
The table shows the compatible valve models:


It is possible to set the stroke value using the parameter "Actuator Stroke". For furthermore details see the paragraph MODBUS PARAMETERS.

WARNING In case of MVC used on a valve produced before September 2019 to replace an MVT, the 55061 kit must be used.

| VALVE (production previous <br> September 2019) | ACTUATOR to be <br> replaced | Replacement KIT |
| :---: | :---: | :---: |
| VSB.T-VMB.T | MVT203 |  |
| 2 2-3TBB.T | MVT403 | 55061 |
| $2-3 T G B . B$ | MVT503 |  |

## MANUFACTURING CHARACTERISTICS

The actuator housing is made of a polymeric fireproof material; a metal ring nut M30x1,5 is dedicated to the connection with the valve.
The actuator is equipped with a 5 wires cable for electric connection.

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The device contains electrical and electronic components and is not allowed to be disposed www.controlli.eu of as household refuse. All locally valid regulations and requirements must be observed.

## SAFETY REQUIREMENTS

1. Install on the power supply line a protecting device to avoid short circuits (fuse or magneto-thermic) according to the specifications;
2. in case of accidental removal of the cover and/or of the connector cover, make sure that power is disconnected before working on the actuator or near it;
3. the products are maintenance free.

## VARIANTS

PS107 actuator with M $28 \times 1,5$ ring nut.

## ACCESSORIES

AG74-03 2-3TGB.B Controlli valves adaptor (N.B. to be used in replacing of the spindle extension provided with the valves).
55061 Kit of adapters for coupling the actuator with VSB.T-VMB.T, 2-3TBB.T and 2-3TGB.B series valves produced before September 2019.

In case of use of non Controlli valves please contact technical secretariat for proper adaptor.

## TECHNICAL CHARACTERISTICS

| Power supply: | $24 \mathrm{Vac} / \mathrm{dc} \pm 10 \%$ |
| :--- | :--- |
| Speed (selectable via Modbus): | $5 \mathrm{~s} / \mathrm{mm}$ (default) or $3 \mathrm{~s} / \mathrm{mm}$ |
| Force: | 300 N (UNI 9497:1989) |
| Cable: | 5 wires 1,5 m (CEl 20-22/II) |
| Weight: | $0,4 \mathrm{~kg}$ |
| Protection degree: | IP54 |
| Feedback signal: | via Modbus |
| Charging time for supercapaci- <br> tors: | $\sim 45 \mathrm{sec}$ |
| Speed in Emergency positioning: | $3 \mathrm{~s} / \mathrm{mm}$ |
| Transformer sizing: | 30 VA |
|  | 12 W |
| Consumptionsupercapacitor <br> charging | moving |
| holding position | $1,5 \mathrm{~W}$ |
| Manual override: | with 3 mm hex key |
| Max stroke: | 12 mm |
| Operation temp: | $-5 \mathrm{~T} 55^{\circ} \mathrm{C}$ |
| Storage temp: | $-25 \mathrm{~T} 65^{\circ} \mathrm{C}$ |
| Reference Directives and <br> Standards: | EMC $2014 / 30 / \mathrm{UE}$ according to <br> EN $61326-1: 2013$ |

## INSTALLATION AND MOUNTING

When assembled with valve with spring, before assembling the valve and the actuator, check that the actuator screw jack is fully retracted. If not, remember that, to mount the actuator on the valve in the right position, you have to overcome the spring force of the valve itself. Screw in the M30x1,5 ring nut firmly on the valve thread.

For all the valves without spring, mount the actuator on the valve screwing in the M30x1,5 ring nut without locking it; using the manual
override make the screw jack go down until to align the actuator spindle slot with the locknut (A), secure with the bolt (B) through threaded hole in locknut (A). Rotate the actuator in the desired position and lock the M30x1,5 ring nut.
Respect the orientation of the actuator shown in the figures below.


## WIRING DIAGRAM

Wiring shall be executed according to the local valid laws. To check the direction of movement of the spindle, compare the direction of rotation of the manual override with the indication on the base. The movement of the valve stem can also be observed through the slots in correspondence with the fixing ring nut.


## SETTINGS AND FUNCTIONS

Actuator settings has to be done via Modbus. The Modbus Database where all the available registers are described is provided at pag. 5. Factory settings are detailed in the table it self.

The default factory setting of the Modbus address is 1 , to modify it follow these instructions:

1. Remove the cover and the connector (look at the following picture).
2. Change the DIP switches as indicated in the DIP SWITCHES table.
3. The new settings will be active on the next power off/on cycle.



Modbus - RS485 Connection
The RS485 network is implemented with a 3-conductor cable, which will be later identified as "+", "-" and "GND".
For wiring is suggested Belden $®$, model 8762.
For "disturbed" areas is suggested a Belden $®$, model 3106A using the twisted pair to connect the " + " and "-", the reference wire to connect to "GND" and the shield to connect to ground.
Alternatively you can use a cable with the following electrical and mechanical characteristics:

- AWG 20/22;
- characteristic impedance of $120 \Omega$;
- copper wire, "plait" type, twisted;
- shielded braided and insulated.

The shield must be connected to controller GND.
The network must be wired only in accordance with the principle shown here, called "daisy chain" (the device is composed by a single RS485 port). Star connections are not allowed.

Connections warnings


For proper network cabling is recommended to take the following precautions:

1. Do not use different types of cable to achieve the same network, but always use only the same type of cable;
2. The network cable carries out safety voltage signals (SELV) and must not be wired together with dangerous voltage signals (e.g., 230 Vac ) or carriers of high currents, especially if in alternating current. Also avoid parallel paths to these power cables;
3. Wire the cable lying avoiding kinks, narrow bending radii and unnecessary wrapping in hanks or skeins;
4. Do not twist the cable cord around the power conductors and, if they should cross, consider an intersection at $90^{\circ}$ between the cable and these conductors;
5. Keep away from sources of electromagnetic field in particular by large motors, electrical cabinet, reactors for neon, all types of antennas;
6. Do not pull the power cable exceeds $110 \mathrm{~N}(11.3 \mathrm{~kg})$ to prevent ironing;
7. Assess in advance the route so that it will be as short as possible and note addresses of connected instruments with particular reference to its location in the orderly sequence. This can be very useful in maintenance; we recommend to note the Modbus Address on the product label.
8. Do not reverse the polarity "+" and "-" of the connection terminals;
9. Avoid short lengths of cable terminations in connection tools to make a maintenance without tearing or flues of the cables possible;
10. Identify start and ending terminations and avoid cuts "open";

Recharge supercapacitors
When the actuator is powered on the supercapacitors charging phase start automatically.

- during the charging phase DL1 (red), DL2 (green), DL3 (yellow) and DL5 (red) are ON (solid);
- charging phase will be completed after about 40 s when DL1 (red), DL2 (green), DL3 (yellow) and DL6 (green) are ON;
- the actuator is ready for operation when DL1 (red), DL2 (green), DL3 (yellow) switch OFF and DL6 (green) is ON.
During the supercapacitors recharge phase, Modbus communica-
tion is not possible.



## Control Position

The position of the actuator can be defined by the BMS through a dedicated Modbus parameter ranging between $0 \%$ and $100 \%$ where $0 \%$ means actuator fully retracted (direct action) and $100 \%$ means actuator fully extended (direct action). If reverse action is enabled $0 \%$ means actuator fully extended and $100 \%$ means actuator fully retracted.

## Calibration

This function allows to detect the maximum valve stroke, so that the actuator can drive the valve correctly following the control signal. If the actuator is powered on, this action can be repeated any time DIP 9 goes from OFF to ON or by setting a specific Modbus parameter (for valves with auto stroke calibration). Maximum valid stroke 12 mm .

Auto stroke calibration / Fixed stroke
Through Modbus the user can choose (on the basis of the coupled valve) if the stroke must be fixed or automatically calibrated. Valve stroke can be set via Modbus at any values ranging from $2,5 \mathrm{~mm}$ and 12 mm .
The actuator can be coupled with valves without spring using auto stroke calibration or to valves with spring return using fixed stroke mode.

Direct/Reverse action
The actuator is supplied without default stroke. Automatic calibration is performed at first power up (Plug and play function).
Direct/reverse action can be set via Modbus. In direct action the actuator is fully retracted when control position is $0 \%$ and valve position feedback is $0 \%$. With reverse action the actuator is fully extended when control position is $0 \%$ and valve position feedback is $0 \%$.

Initial Positioning
It is executed every time the actuator is powered and after the calibration phase. This operation allows the actuator to start from a known position and then follow the command signal. This position depends on the selection of direct or reverse action.

## Unexpected stall condition

If an unexpected stop during the stroke occurs, this function has the aim to make it disappear. The actuator will be driven in the opposite direction and then it will try again to reach the position.
If it was not unlocked after the first 3 attempts, after a 1 minute pause, 3 more attempts are made.

## Valve Position Feedback

The feedback of the current valve position is made available by a specific Modbus parameters ranging from 0 to 1000 (dividing this value by 10 gives the feedback value as a percentage). During the "automatic stroke calibration" and "Initial positioning" function it is set at 1200 (corresponding to $120 \%$ ). During the emergency positioning function the feedback parameter is set to 11100 (corresponding to $110 \%$ ).

## Manual override

To activate the manual override, remove the power supply, remove the transparent cover and insert a 3 mm hexagonal key into the front hole and turn the key until the desired position is reached.

Plug \& Play
Automatic calibration is performed at the very first power up.

Actuator Speed setting
The speed of the actuator can be set via Modbus from $5 \mathrm{~s} / \mathrm{mm}$ (default value) to $3 \mathrm{~s} / \mathrm{mm}$.

Linear/Equipercentage
Actuator position characteristic is normally linear, but MVC503R-MB allow to set an equipercentage behaviour allowing to make a linear valve working like an equipercentage valve.


Diagnostic Functions
MVC503R-MB offer a number of diagnostic functions made available through Modbus:

- "Actuator Status" (similar to LED behaviour);
- "No. of Openings" showing how many times the actuator has been fully retracted
- "No. of Closing" showing how many times the actuator has been fully extended;
- "First Power up" showing if the actuator has been powered for the first time or not;
- "Low voltage anomaly" showing how many times the power supply voltage has been lower than the specified range (also includes low voltage due to emergency return);
- "High voltage anomaly" showing how many times the power supply voltage has been higher than the specified range;
- "Unexpected stalls" showing how many times the actuator detected unxepected stalls during operations;
- "Extra-stroke" showing how many times the actuators detected a stroke higher than the last calibrated stroke;
- "Calibration Error" showing how many times the calibrated stroke failed because the actuator stroke is outside the range.


## LED BEHAVIOUR



| Description | DL5 (red) | DL6 (green) |
| :--- | :---: | :---: |
| Emergency return phase / Supercapa- <br> citor charging phase | ON | OFF |
| Supercapacitor charging phase <br> completed | OFF | ON |



| Address | Modbus Register | Description | Range | Default | RD/WR | Persistence |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 6678 \\ & 6679 \\ & 6680 \end{aligned}$ | Firmware version | "Firmware version (composed of 3 bytes): <br> ${ }^{\text {st }}$ byte: major version <br> $2^{\text {nd }}$ byte: minor version <br> $3^{\text {rd }}$ byte: revision version" | 0-FFFFFF | 0xFFFFFF | RD | YES |
| 6681 | First power up | Represents the first power up event | 0xCF value | 0xFF | RD | YES |
| 6682 | Calibration error | Represents the number of times a stroke error has occurred down the minimum allowed | 0-FE | 0xFF | RD | YES |
| 6683 | Calibration error | Represents the number of times a stroke error has occurred up the maximum allowed | O-FE | 0xFF | RD | YES |
| 6684 | Low voltage anomaly | Represents the number of times a low voltage event has occurred | O-FE | 0xFF | RD | YES |
| 6685 | High voltage anomaly | Represents the number of times a high voltage event has occurred | 0-FE | 0xFF | RD | YES |
| 6686 | Unexpected stalls within the race | Represents the number of times a stall has occurred within the run | 0-FE | 0xFF | RD | YES |
| 6687 | Extra stroke in normal operation | Represents the number of times that an extra stroke error has occurred compared to that calculated during the calibration phase (stroke out of range) | O-FE | 0xFF | RD | YES |
| 6688 | Actuator stroke | "Identifies the value read by the actuator after the calibration phase. <br> It is possible to set the stroke value but requires restarting the actuator. <br> The value must be stored multiplied by 10." | $\begin{gathered} 20-120 \\ (2 \mathrm{~mm}-12 \mathrm{~mm}) \end{gathered}$ | FF (there is no need to initialize the value) | RD/WR | YES |
| 6689 | Actuator setting | Direct/reverse action setting | 0-15 | Direct action (bit0=1) | RD/WR | YES |
|  |  | Forcing calibration phase |  | Calibration not enabled (bitl=1) |  |  |
|  |  | Emergency return direction selection (up or down) |  | Down (bit2=1) |  |  |
|  |  | Fixed stroke |  | Fixed stroke not enabled (bit3=1) |  |  |
| 6690 | Actuator speed | Allows you to set the speed of the actuator | $\begin{gathered} 207(5 \mathrm{~s} / \mathrm{mm}) \\ \text { or } \\ 119(3 \mathrm{~s} / \mathrm{mm}) \end{gathered}$ | $\begin{gathered} " 207 \\ (5 \mathrm{~s} / \mathrm{mm}) \text { " } \end{gathered}$ | RD/WR | YES |
| 6691 | LIBRA valve type configuration | By selecting the type of PICV LIBRA valve, the stroke value is automatically set to 4 mm and reverse action | 0-1 | 0 (NOPICV) | RD/WR | YES |
| 6692 | Characteristic configuration of the valve ( $\beta$ ) | It represents the characteristic of the valve ( $\beta=0$ linear valve, $\beta=1$ equal percentage valve) | 0-1 | 0 | RD/WR | YES |
| 6693 | Baud rate | Represents the communication speed of the Modbus protocol $(9600,19200)$ | 0-2 | $0 \times 00$ | RD/WR | YES |
| 6694 | Parity bit and stop bit | 2 least significant bits (bits 0 and 1): parity bit ( $0=$ none, $1=$ even, $2=$ odd) bit 4: stop bit ( $0=1$ stop bit, $1=2$ stop bit) | 0-16 | 16 | RD/WR | YES |
| 6146 | Opening phase | It is the number of times the actuator has been in the total opening position | 0-65279 | 0xFFFF | RD | YES |
| 6147 | Closing phase | It is the number of times the actuator has been in the total closing position | 0-65279 | 0xFFFF | RD | YES |
| 8840 | Actuator control | Represents the percentage of control of the actuator (by setting a value between 0 and $100 \%$ it allows to drive the motor in any position) | 0-100\% | 0 | RD/WR | NO |
| 8841 | Actuator operating status | Represents the current operating status of the actuator (based on the status of the LEDs) | 0-16 | 0xFF | RD | NO |
| 8842 | Reset actuator | Allows you to perform a software reset of the actuator | 0-1 | 0 | RD/WR | NO |
| 8288 | Valve position (feeback) | Represents the position of the actuator | 0-1000 (divide by 10 to have a\% value) (calibration 1200, emergency return 1100) | FF (there is no need to initialize the value) | RD | NO |
| 8289 | Valve flow rate | In the case of selection of the PICV, it represents the percentage flow rate value (the value of the feedback register is not available) | $0-1000$ <br> (dividere per 10 per aver valore \%) | FF (there is no need to initialize the value) | RD | NO |


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| DIP8 | DIP7 | DIP6 | DIP5 | DIP4 | DIP3 | DIP2 | DIP1 | MODBUS ADDRESS |
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| ON | OFF | OfF | OfF | OfF | OfF | ON | ON | 131 |
| ON | OfF | OFF | OFF | OFF | ON | OFF | OFF | 132 |
| ON | OfF | OFF | OFF | OFF | ON | OFF | ON | 133 |
| ON | OfF | OFF | OFF | OFF | ON | ON | OfF | 134 |
| ON | OfF | OFF | OFF | OFF | ON | ON | ON | 135 |
| ON | OfF | OFF | OFF | ON | OfF | OfF | OfF | 136 |
| ON | OfF | OFF | OFF | ON | OfF | OFF | ON | 137 |
| ON | OfF | OFF | OFF | ON | OFF | ON | OfF | 138 |
| ON | OfF | OFF | OFF | ON | OFF | ON | ON | 139 |
| ON | OfF | OFF | OFF | ON | ON | OFF | OFF | 140 |
| ON | OfF | OFF | OFF | ON | ON | OfF | ON | 141 |
| ON | OfF | OFF | OFF | ON | ON | ON | OFF | 142 |
| ON | OfF | OFF | OfF | ON | ON | ON | ON | 143 |
| ON | OfF | OFF | OfF | OfF | OfF | OfF | OfF | 144 |
| ON | OfF | OFF | OFF | OFF | OFF | OFF | ON | 145 |
| ON | OfF | OFF | OFF | OFF | OFF | ON | OfF | 146 |
| ON | OfF | OFF | OFF | OFF | OfF | ON | ON | 147 |
| ON | OFF | OfF | OfF | OFF | ON | OfF | OfF | 148 |
| ON | OfF | OFF | OFF | OFF | ON | OFF | ON | 149 |
| ON | OfF | OFF | OFF | OFF | ON | ON | OFF | 150 |
| ON | OfF | OFF | OFF | OFF | ON | ON | ON | 151 |
| ON | OfF | OFF | ON | ON | OfF | OfF | OfF | 152 |
| ON | OfF | OfF | ON | ON | OFF | OFF | ON | 153 |
| ON | OfF | OFF | ON | ON | OFF | ON | OfF | 154 |
| ON | OfF | OFF | ON | ON | OFF | ON | ON | 155 |
| ON | OfF | OfF | ON | ON | ON | OfF | OfF | 156 |
| ON | OfF | OfF | ON | ON | ON | OFF | ON | 157 |
| ON | OfF | OfF | ON | ON | ON | ON | OfF | 158 |
| ON | OfF | OFF | ON | ON | ON | ON | ON | 159 |
| ON | OfF | OFF | ON | OFF | OfF | OfF | OfF | 160 |
| ON | OfF | OfF | ON | OFF | OFF | OFF | ON | 161 |
| ON | OfF | OfF | ON | OFF | OFF | ON | OfF | 162 |
| ON | OfF | OfF | ON | OFF | OFF | ON | ON | 163 |
| ON | OFF | OFF | ON | OFF | ON | OfF | OfF | 164 |
| ON | OfF | OfF | ON | OfF | ON | OfF | ON | 165 |
| ON | OfF | OfF | ON | OFF | ON | ON | OfF | 166 |
| ON | OfF | OFF | ON | OFF | ON | ON | ON | 167 |
| ON | OfF | ON | OfF | ON | OfF | OFF | OFF | 168 |
| ON | OfF | ON | OfF | ON | OFF | OFF | ON | 169 |
| ON | OfF | ON | OfF | ON | OFF | ON | OFF | 170 |
| ON | OfF | ON | OfF | ON | OfF | ON | ON | 171 |
| ON | OfF | ON | OfF | ON | ON | OfF | OfF | 172 |
| ON | OFF | ON | OfF | ON | ON | OFF | ON | 173 |
| ON | OfF | ON | OfF | ON | ON | ON | OfF | 174 |
| ON | OfF | ON | OfF | ON | ON | ON | ON | 175 |
| ON | OfF | ON | OfF | OfF | OfF | OFF | OfF | 176 |
| ON | OfF | ON | OFF | OFF | OFF | OFF | ON | 177 |
| ON | OfF | ON | OFF | OFF | OFF | ON | OFF | 178 |
| ON | OfF | ON | OFF | OFF | OFF | ON | ON | 179 |
| ON | OfF | ON | OFF | OFF | ON | OfF | OfF | 180 |
| ON | OfF | ON | OFF | OFF | ON | OFF | ON | 181 |
| ON | OfF | ON | OFF | OFF | ON | ON | OfF | 182 |
| ON | OFF | ON | OFF | OFF | ON | ON | ON | 183 |
| ON | OfF | ON | ON | ON | OfF | OfF | OfF | 184 |
| ON | OfF | ON | ON | ON | OfF | OFF | ON | 185 |
| ON | OfF | ON | ON | ON | OfF | ON | OfF | 186 |
| ON | OfF | ON | ON | ON | OFF | ON | ON | 187 |
| ON | OfF | ON | ON | ON | ON | OFF | OfF | 188 |
| ON | OfF | ON | ON | ON | ON | OfF | ON | 189 |
| ON | OFF | ON | ON | ON | ON | ON | OFF | 190 |
| ON | OFF | ON | ON | ON | ON | ON | ON | 191 |
| ON | OfF | ON | ON | OFF | OFF | OFF | OfF | 192 |
| ON | OFF | ON | ON | OFF | OFF | OFF | ON | 193 |
| ON | OfF | ON | ON | OFF | OFF | ON | OFF | 194 |
| ON | OfF | ON | ON | OFF | OFF | ON | ON | 195 |
| ON | OfF | ON | ON | OFF | ON | OFF | OfF | 196 |
| ON | OfF | ON | ON | OFF | ON | OFF | ON | 197 |


| DIP8 | DIP7 | DIP6 | DIP5 | DIP4 | DIP3 | DIP2 | DIP1 | MODBUS ADDRESS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ON | OfF | ON | ON | OFF | ON | ON | OfF | 198 |
| ON | ON | ON | ON | OFF | ON | ON | ON | 199 |
| ON | ON | OFF | OFF | ON | OFF | OFF | OFF | 200 |
| ON | ON | OFF | OFF | ON | OFF | OFF | ON | 201 |
| ON | ON | OFF | OFF | ON | OFF | ON | OfF | 202 |
| ON | ON | OFF | OFF | ON | OFF | ON | ON | 203 |
| ON | ON | OFF | OFF | ON | ON | OFF | OFF | 204 |
| ON | ON | OFF | OFF | ON | ON | OFF | ON | 205 |
| ON | ON | OFF | OFF | ON | ON | ON | OFF | 206 |
| ON | ON | OFF | OFF | ON | ON | ON | ON | 207 |
| ON | ON | OfF | OFF | OFF | OFF | OFF | OfF | 208 |
| ON | ON | OFF | OFF | OFF | OFF | OFF | ON | 209 |
| ON | ON | OFF | OFF | OFF | OFF | ON | OFF | 210 |
| ON | ON | OFF | OFF | OFF | OFF | ON | ON | 211 |
| ON | ON | OFF | OFF | OFF | ON | OFF | OfF | 212 |
| ON | ON | OfF | OfF | OfF | ON | OfF | ON | 213 |
| ON | ON | OfF | OfF | OFF | ON | ON | OFF | 214 |
| ON | ON | OfF | OFF | OFF | ON | ON | ON | 215 |
| ON | ON | OFF | ON | ON | OFF | OFF | OfF | 216 |
| ON | ON | OFF | ON | ON | OFF | OFF | ON | 217 |
| ON | ON | OFF | ON | ON | OFF | ON | OFF | 218 |
| ON | ON | OfF | ON | ON | OFF | ON | ON | 219 |
| ON | ON | OfF | ON | ON | ON | OFF | OfF | 220 |
| ON | ON | OfF | ON | ON | ON | OFF | ON | 221 |
| ON | ON | OfF | ON | ON | ON | ON | OfF | 222 |
| ON | ON | OfF | ON | ON | ON | ON | ON | 223 |
| ON | ON | OFF | ON | OfF | OfF | OFF | OfF | 224 |
| ON | ON | OFF | ON | OFF | OFF | OFF | ON | 225 |
| ON | ON | OFF | ON | OFF | OFF | ON | OfF | 226 |
| ON | ON | OFF | ON | OFF | OFF | ON | ON | 227 |
| ON | ON | OfF | ON | OFF | ON | OFF | OfF | 228 |
| ON | ON | OfF | ON | OFF | ON | OFF | ON | 229 |
| ON | ON | OfF | ON | OFF | ON | ON | OfF | 230 |
| ON | ON | OFF | ON | OFF | ON | ON | ON | 231 |
| ON | ON | ON | OfF | ON | OfF | OFF | OfF | 232 |
| ON | ON | ON | OFF | ON | OfF | OFF | ON | 233 |
| ON | ON | ON | OFF | ON | OFF | ON | OfF | 234 |
| ON | ON | ON | OFF | ON | OFF | ON | ON | 235 |
| ON | ON | ON | OFF | ON | ON | OFF | OfF | 236 |
| ON | ON | ON | OFF | ON | ON | OFF | ON | 237 |
| ON | ON | ON | OFF | ON | ON | ON | OfF | 238 |
| ON | ON | ON | OFF | ON | ON | ON | ON | 239 |
| ON | ON | ON | OFF | OFF | OFF | OFF | OfF | 240 |
| ON | ON | ON | OFF | OFF | OFF | OFF | ON | 241 |
| ON | ON | ON | OFF | OFF | OFF | ON | OfF | 242 |
| ON | ON | ON | OFF | OFF | OFF | ON | ON | 243 |
| ON | ON | ON | OfF | OfF | ON | OfF | OfF | 244 |
| ON | ON | ON | OFF | OFF | ON | OFF | ON | 245 |
| ON | ON | ON | OfF | OFF | ON | ON | OfF | 246 |
| ON | ON | ON | OFF | OFF | ON | ON | ON | 247 |
| ON | ON | ON | ON | ON | OFF | OFF | OfF | 248 |
| ON | ON | ON | ON | ON | OFF | OFF | ON | 249 |
| ON | ON | ON | ON | ON | OFF | ON | OfF | 250 |
| ON | ON | ON | ON | ON | OfF | ON | ON | 251 |
| ON | ON | ON | ON | ON | ON | OFF | OfF | 252 |
| ON | ON | ON | ON | ON | ON | OFF | ON | 253 |
| ON | ON | ON | ON | ON | ON | ON | OfF | 254 |
| ON | ON | ON | ON | ON | ON | ON | ON | 255 |


| DIP9 | FUNCTION |
| :---: | :---: |
| ON | Auto stroke calibration |

ATTENTION: When auto stroke calibration start move DIP9 to OFF. With auto stroke DIP9 carries out initial positioning and learning, with fixed stroke it only carries out initial positioning.

The performances stated in this sheet can be modified without any prior notice

