



| MODEL | FORCE [N] | POWER SUPPLY | DESCRIPTION |
|--------|-----------|--------------|---------------------|
| MVH56E | 1500 | 24Vac/dc | Modulating/floating |
| MVHE3K | 3000 | 24Vac/dc | Modulating/floating |

APPLICATION AND USE

MVH56E and MVHE3K are flexible electro-mechanical actuators for the control of two-way and three-way globe valves in:

- heating and cooling systems;
- Air Handling Units;
- district heating plants;
- industrial temperature control systems.

MVH56E and MVH3K can be controlled either by a proportional (modulating) signal or by an increase/decrease (floating) signal. It is easy to mount and connect the actuators. Direct mounting is possible to any CONTROLLI flanged valve as well as for valves of other manufacturers (contact our Technical Dept.). The actuators have a fine resolution (500 steps on the full stroke range) for exacting fluid control and they are able to self-calibrate on a different stroke without the need of any user action (this function is selectable on the field via DIP switch).

MVH56E and MVH3K have intelligent behavior and alarm functionality in case of unexpected operation, feedback of alarms to the user is provided by two LEDs (GREEN and RED) on the control board.
N.B.: Do not use the actuator if not coupled with its relating valve.

OPERATION

The actuators translate the control signal (modulating or 3 point floating) from the controller into a valve position. A modern brushless DC motor in the actuator drive a gear train and a worm gear – screw jack mechanism convert the motor revolutions into accurate and repeatable linear movements.

Control Signal

MVH56Ex can be controlled by two main control types.

- 3 point floating ;
- Modulating (or proportional) signal with filed selectable range (e.g., 0-10Vdc, 2-10Vdc, 0-5/2-6Vdc, 5-10/6-10Vdc e 4-20mA.)

Feedback Signal

The actuator utilizes a 2-10V position feedback (look at DIP n. 1 settings).

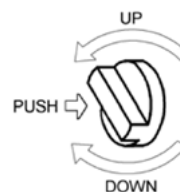
Calibration

MVH56E and MVHE3K are endowed with an automatic stroke calibration function, but they can be calibrated also manually via DIP n. 7. In factory delivery the auto stroke calibration is enabled; manual calibration is not necessary unless maintenance is required on the valve or certain alarm functions are desired.



Manual Override

The manual control can be activated only after disconnecting power supply. To use the manual override, it is necessary to push and hold down the knob; turn clockwise to move the valve stem downwards and counter clockwise to move it upwards (see the picture). Be careful not to force the manual override when the actuator stroke end is reached.



MANUFACTURING CHARACTERISTICS

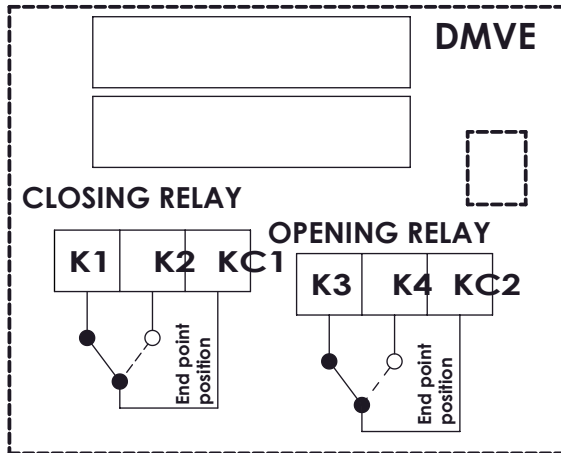
The actuator consists in a die-cast aluminium housing, which includes the mounting bracket for connection to valve body. Reduction gears supported by ball bearings. Movement is transmitted to a rack-and-pinion mechanism connected to the valve stem through a suitable joint.

Internal electronic card with easily accessible terminals for electrical connections.

End Point Auxiliary Switches (accessory DMVE)

End point switches change over when the valve is fully open or closed. They are free contacts with 24Vac max voltage on terminals. End point switches can be utilized to indicate valve stroke end positions and for relay control of additional plant equipment. When the actuators are controlled individually or in sequence, it is possible to use the end switches to toggle when the valve is fully open or fully closed. The auxiliary switch position according to control signal (Y) is shown in the table below.

| Control signal (Y) | Relay KC1 | Relay KC2 |
|--------------------|-----------|-----------|
| 0-0,5Vdc | KC1 to K2 | KC2 to K3 |
| 0,5-9,5Vdc | KC1 to K1 | KC2 to K3 |
| 9,5-10Vdc | KC1 to K1 | KC2 to K4 |



Diagnostic

The actuator is provided with a self diagnostic algorithm able to detect faulty conditions:

- stroke out of range 5-60 mm;
- unexpected stall condition (e.g., valve stuck);
- missing expected stall condition (e.g., link loose);
- voltage supply out of range.

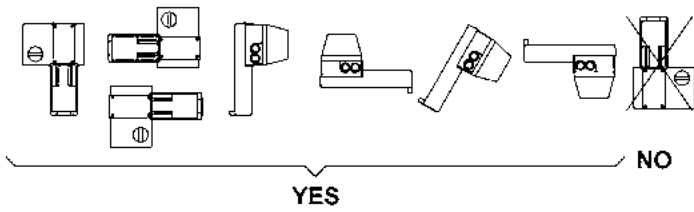
These faulty conditions are signalled via the GREEN and RED LED on the electronic board blinking accordingly (see "Diagnostic – Alarm Function Table").

TECHNICAL CHARACTERISTICS

| | MVH56E | MVHE3K |
|-----------------------|--|-----------|
| Supply voltage L1 Ln | AC: 24Vac ±20% 50-60Hz DC: 22-30Vdc (Reference Ln) | |
| Power consumption | 12VA/5.2W | 17VA/8.5W |
| Modulating 5-15mm | 15s | |
| Modulating 15-25mm | 25s | |
| Modulating 25-40mm | 35s | |
| Modulating 40-60mm | 50s | |
| Floating | 60s | |
| Transformer Size [VA] | 50 | 60 |
| Stroke | 5-60mm | |
| Force [N] | 1500 | 3000 |
| Duty cycle | max 50%/60 minutes | |
| Analogue input Y M | Voltage 0-10V - impedance > 100kΩ (range: 0-10 2-10 0-5/2-6 5-10/6-10) 500Ω (range 4-20mA) | |
| Digital inputs Y1-Y2 | Connection to L1 or Ln when powered in AC Connection to Ln only when powered in DC | |
| Output V+ | Voltage 16Vdc ± 0,5V Max Load 25mA, | |
| Output U | Voltage 2-10Vdc (0-100%) Max Load 2mA | |
| Cable glandes | plastic punchable, replaceable by PG13,5 compression glands | |
| Type of movement | linear | |
| Ambient temperature | Operation and storage -10/+50°C | |
| Ambient Humidity | max 90% RH | |
| Protection degree | IP55 DIN40050 (IEC 529) for highly polluted environments according to IEC 730-1 (93)/6,5,3 | |
| Insulation class | III | |
| Standard | Emission/Immunity EMC 2004/108/CE according to EN 61326-1:2006 standard | |
| Weight [kg] | 4 | |
| Dimensions [mm] | Refer to the picture on page x | |

ASSEMBLING

The actuator can be mounted in the positions shown picture below:



It is advisable to use the motorized valve with MVHT spacer, in order to reduce the actuator working temperature in case of fluids at high temperatures (approximately > 120° C) in the valve body. For fluids over 160 °C avoid mounting the actuator in vertical position on the valve so as to avoid the direct exposure to heat sources. For further information look at mounting instructions (MVH56E-MVHE3K_DIM263).

MAINTENANCE

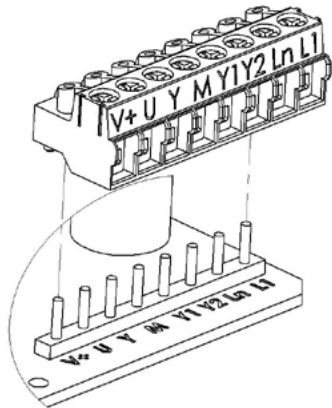
The actuator is maintenance-free.

ACCESSORIES

- DMVE** Endpoint Auxiliary Switches
- 248** Yoke Heater (Suggested when the fluid temperature is below 0°C)
- GMVH** Insulation shell for MVH actuators

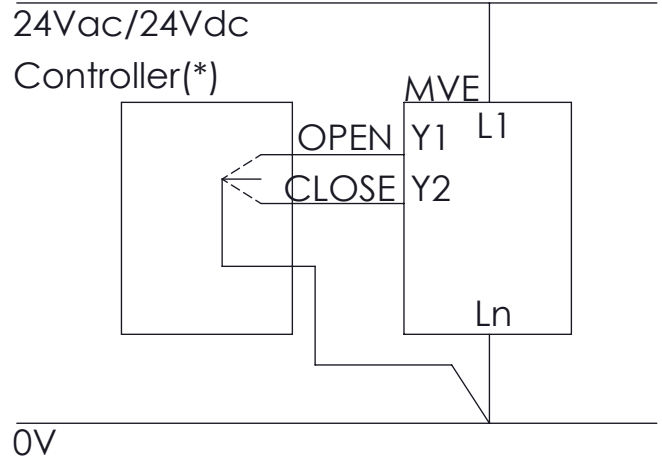
ELECTRIC CONNECTIONS

Carry out the electrical connections by removing the cover, in compliance with the rules in force. The actuator is equipped with a 8 poles removable terminal block; the each pole of the plug is clearly marked and the same label are reported on the electric board. Before powering up the actuator make sure the plug is properly connected to the board and the label on the plugs and on the board match.

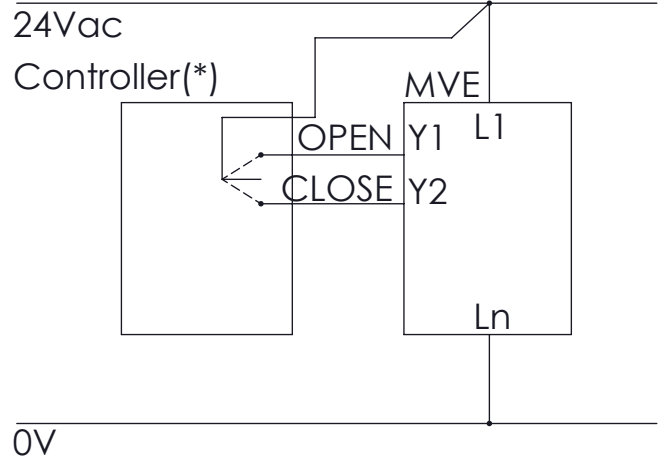


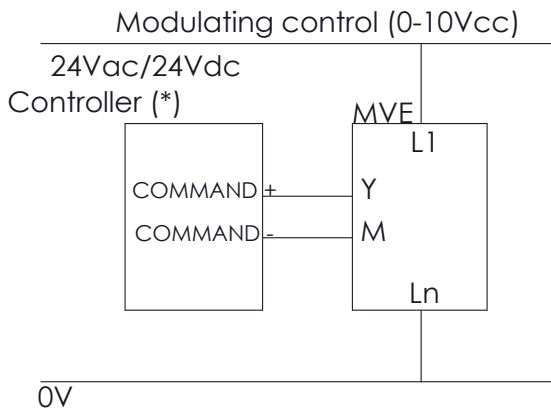
| Label | Description | Function | Cable type | Max wire Length |
|-------|-------------|--------------------------|--|-----------------|
| L1 | 24Vac/dc | Power Supply | AWG 16 (min 1mm ² - max 1.5mm ²) | 75m |
| Ln | 0V | | | |
| Y | 0-10Vdc | Modulating Control Input | AWG 20 (min 0,5mm ² - max 1.5mm ²) | 200m |
| M | 0V (Common) | | | |
| Y1 | Open | Floating Control Input | AWG 20 (min 0,5mm ² - max 1.5mm ²) | 200m |
| Y2 | Close | | | |
| V+ | 16 Vdc | Voltage Output max 25mA | AWG 20 (min 0,5mm ² - max 1.5mm ²) | 200m |
| M | 0V (Common) | | | |
| U | 2-10Vdc | Feedback Output Signal | AWG 20 (min 0,5mm ² - max 1.5mm ²) | 200m |
| M | 0V (Common) | | | |

3-point floating control (sink connection)



3-point floating control (source connection)



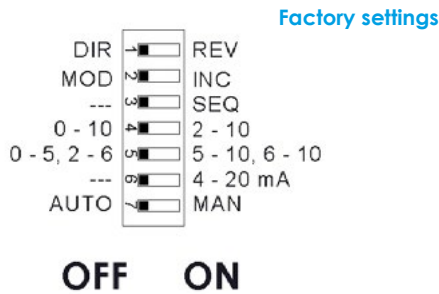


N.B: M and Ln signal are internally connected.

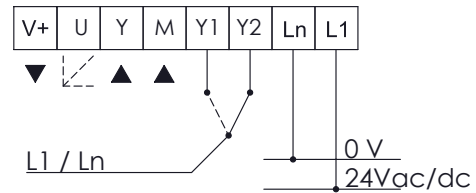
(*) MVH56E and MVHE3K actuators contain a half-wave rectifier power supply. They must not be powered with transformers that are used to power other devices using not isolated full-wave rectifier power supply.

DIP SWITCHES SETTINGS

Set the DIP switches according to the tables here below. Power down and power up again the actuator or act on the manual operation handle to be sure that settings will be recognized.

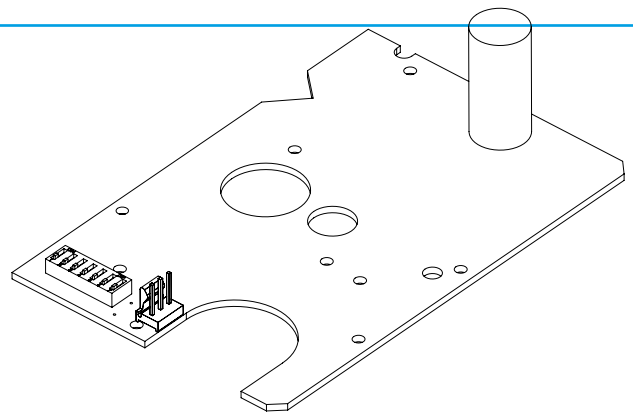


TERMINAL BLOCK



Matching between MVH56E and MVHE3K terminal block and other Controlli actuators

| | | | | | | | | |
|----|----|----|----|----|----|----|---|---------------|
| G | G0 | MX | G1 | X1 | VH | VC | Y | MVH56F |
| G | G0 | MX | G1 | X1 | VH | VC | Y | MVH3K |
| L1 | LN | M | V+ | Y | Y1 | Y2 | U | MVH56E/MVHE3K |



| DIP switch | OFF | ON |
|------------|--|---|
| 1 | <p>Direct Action</p> <p>U= feedback</p> <p>U = 2V</p> <p>U = 10V</p> | <p>Reverse Action</p> <p>U= feedback</p> <p>U=10V</p> <p>U = 2V</p> |
| 2 | <p>Modulating Control (MOD) (Input between Y [+] and M [-])</p> | <p>3 point floating (INC) (Y1 open-extend , Y2 close-retract connected L1 or Ln if powered in Vac; if powered in Vdc connected necessarily to Ln)</p> |
| 3 | - | Selection of sequence mode, control range defined by SW 5 |
| 4 | Modulating Control 0-10Vdc (DIP n. 2 OFF only) | Modulating Control 2-10Vdc (DIP n. 2 OFF only) |
| 5 | Sequence Control 0-5Vdc with DIP n. 4 OFF only Sequence Control 2-6Vdc with DIP n. 4 ON only (DIP n. 3 ON only) | Sequence Control 5-10Vdc with DIP n. 4 OFF only Sequence Control 6-10Vdc with DIP n. 4 ON only (DIP n. 3 ON only) |
| 6 | Voltage Input Signal (input between Y [+] and M [-]) | Current Input Signal 4-20mA (input between Y [+] and M [-]). In this case DIP n. 4 must be set to ON. |
| 7 | Automatic Calibration: the actuator updates the stroke range every time an unexpected mechanical stop is detected for at least 10s | Manual Calibration: the actuator calibration is started moving the DIP from OFF to ON; if the DIP is left in ON the actuator will never update the calibrated stroke value even when an unexpected endpoint is detected |

| N° | LED behaviour | Error | Actuator use | Actuator Behaviour | | Typical trouble shooting condition | Reset procedure |
|----|-------------------------------|---|------------------------------------|---|---|--|---------------------------------|
| | | | | Automatic Calibration DIP N. 7 OFF | Manual Calibration DIP N. 7 ON | | |
| 1 | RED ON | valve stroke less than 5mm | Calibration/ first installation | The actuator pushes/pulls 5 times (unexpected stall) trying to remove the possible obstacle. After 5 tries an alarm is signalled (RED LED ON) and the actuator moves to initial position and does not respond to control signal. Stroke value is not updated because out of range | The actuator pushes/pulls 2 times against endpoint during calibration. Alarm is signalled (RED LED ON) and the actuator moves to the initial position and then it does not respond to the control signal | Valve with a stroke length lower than 5mm | Remove power and power up again |
| 2 | RED ON | Stroke longer than 60mm | Calibration/ first installation | The actuator exits the 60 mm stroke range and it moves toward the new stroke limit signalling an anomaly (RED LED ON). The actuator does not calibrate the stroke | The actuator pushes/pulls 2 times against endpoint during calibration. Alarm is signalled (RED LED ON) and the actuator moves to the initial position and then it does not respond to the control signal | Valve with a stroke length longer than 60mm | Remove power and power up again |
| 3 | RED Quick Blinking + GREEN ON | Unexpected stall within the calibrated stroke range | normal operation | The actuator tries 5 times against the new stall condition and then after 10s the actuator updates the new stroke length; During these 10s RED LED is ON | The actuator tries 5 times against the new stall condition. At the end of the attempts the fault will be signalled (RED LED ON). The actuator does not update the new stroke length, but after 60s makes other attempts to verify the stall condition | Valve stuck | Inverted control signal |
| 4 | RED Quick Blinking + GREEN ON | Stroke longer than expected | normal operation | The actuator moves toward the new stall condition with a lower speed; after 10s the actuator updates the new stroke value; During these 10s RED LED is ON | The actuator moves toward the new stall condition with a lower speed; after 10s the actuator does not update the new stroke value | stem connection loose or valve damaged | Inverted control signal |
| 5 | RED slow Blinking | Low Power Voltage | normal operation | The actuator is still working but performance cannot be guaranteed | The actuator is still working but performance cannot be guaranteed | 1. Wrong transformer size 2. Unstable power | Correct Voltage Power |
| 6 | RED slow Blinking | High Power Voltage | normal operation | The actuator is still working but performance cannot be guaranteed | The actuator is still working but performance cannot be guaranteed | 1. Wrong transformer size 2. Unstable power | Correct Voltage Power |

| N° | LED | ACTUATOR STATUS |
|----|--------------------|---|
| 1 | GREEN ON | The actuator arrived at the extreme point of the stroke read |
| 2 | GREEN BLINKING | The actuator arrived at the intermediate point of the stroke read |
| 3 | RED GREEN BLINKING | The actuator is reading the stroke or it is going to initial position |
| 4 | RED GREEN ON | Manual control ON, the actuator ignores the control signal. ATTENTION! The electronic board is electrically supplied |

DIMENSIONS [mm]

