

Configurable damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 1.5 m<sup>2</sup>
- Torque motor 8 Nm
- Nominal voltage AC/DC 24 V
- Control modulating 2...10 V variable
- Position feedback 2...10 V variable
- Running time motor 4 s variable


**Technical data**

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	13 W
	Power consumption in rest position	2 W
	Power consumption for wire sizing	23 VA
	Power consumption for wire sizing note	I <sub>max</sub> 20 A @ 5 ms
	Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>
	Parallel operation	Yes (note the performance data)
<b>Functional data</b>	Torque motor	8 Nm
	Torque variable	25%, 50%, 75% reduced
	Operating range Y	2...10 V
	Input Impedance	100 kΩ
	Options positioning signal	Open/close Modulating (DC 0...32 V)
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.5...8 V End point 2.5...10 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)
	Direction of motion variable	electronically reversible
	Manual override	with push-button, can be locked
	Angle of rotation	Max. 95°
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops
	Minimum angle of rotation	Min. 30°
	Running time motor	4 s / 90°
	Running time motor variable	4...20 s
	Adaptation setting range	manual (automatic on first power-up)
	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the gear disengagement button
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%
	Override control variable	MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX
Sound power level, motor	56 dB(A)	
Mechanical interface	Universal shaft clamp reversible 8...26.7 mm	
Position indication	Mechanically, pluggable	
<b>Safety</b>	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
	Protection class UL	UL Class 2 Supply

Technical data

<b>Safety</b>	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
	Ambient temperature	-30...40°C
	Ambient temperature note	Caution: +40...+50°C utilisation possible only under certain restrictions. Please contact your supplier.
	Storage temperature	-40...80°C
	Ambient humidity	Max. 95% r.H., non-condensing
Servicing	maintenance-free	
<b>Weight</b>	Weight	1.1 kg

Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

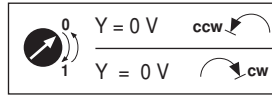
Product features

<b>Mode of operation</b>	The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0.5...100% and as slave control signal for other actuators.
<b>Parametrisable actuators</b>	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
<b>Simple direct mounting</b>	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
<b>Manual override</b>	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
<b>Adjustable angle of rotation</b>	Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of 30° must be allowed for.

**Product features**

**High functional reliability** The actuator is overload protected, requires no limit switches in intermediate positions and automatically stops when the end stop is reached (at rest).

**Home position** The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range. The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics. The actuator then moves into the position defined by the positioning signal.



**Adaption and synchronisation** An adaption can be triggered manually by pressing the “Adaption” button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

**Accessories**

	Description	Type
<b>Electrical accessories</b>	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Auxiliary switch 2 x SPDT add-on, grau	S2A/300 GR
	Auxiliary switch 2 x SPDT add-on, grau	S2A/500 GR
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 140 Ω add-on, grau	P140A GR
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 500 Ω add-on	P500A
	Feedback potentiometer 500 Ω add-on, grau	P500A GR
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 1 kΩ add-on, grau	P1000A GR
	Feedback potentiometer 2.8 kΩ add-on	P2800A
	Feedback potentiometer 2.8 kΩ add-on, grau	P2800A GR
	Feedback potentiometer 5 kΩ add-on	P5000A
	Feedback potentiometer 5 kΩ add-on, grau	P5000A GR
	Feedback potentiometer 10 kΩ add-on	P10000A
	Feedback potentiometer 10 kΩ add-on, grau	P10000A GR
	Adapter for auxiliary switch and feedback potentiometer	Z-SPA
	Signal converter voltage/current 100 kΩ Supply AC/DC 24 V	Z-UIC
	Range controller for wall mounting	SBG24
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
<b>Mechanical accessories</b>	<b>Description</b>	<b>Type</b>
	Actuator arm for standard shaft clamp (one-sided)	AH-25
	Shaft extension 240 mm Ø20 mm for damper shaft Ø 8...22.7 mm	AV8-25
	Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-NSA
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-NSA
Form fit insert 16x16 mm, Multipack 20 pcs.	ZF16-NSA	

Accessories

	Description	Type
	Mounting kit for linkage operation for flat installation	ZG-NMA
	Position indicator, Multipack 20 pcs.	Z-PI
Service Tools	Description	Type
	Service Tool, with ZIP-USB function	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C
	* Adapter Z-SPA It is imperative that this adapter will be ordered if an auxiliary switch or a feedback potentiometer is required and if at the same time the shaft clamp is installed on the rear side of the actuator (e.g. with short-axis installation).	

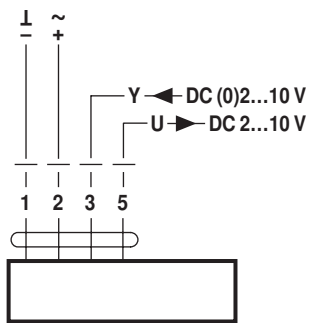
Electrical installation



- Notes**
- Connection via safety isolating transformer.
  - Parallel connection of other actuators possible. Observe the performance data.

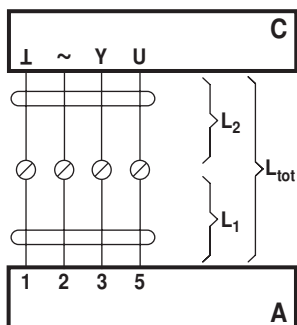
Wiring diagrams

AC/DC 24 V, modulating



**Cable colours:**  
1 = black  
2 = red  
3 = white  
5 = orange

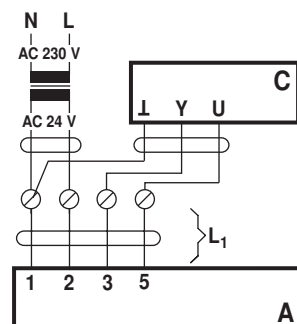
Signal cable lengths



L <sub>2</sub> ┌ / ~	L <sub>tot</sub> = L <sub>1</sub> + L <sub>2</sub>	
	AC	DC
0.75 mm <sup>2</sup>	≤30 m	≤5 m
1.00 mm <sup>2</sup>	≤40 m	≤8 m
1.50 mm <sup>2</sup>	≤70 m	≤12 m
2.50 mm <sup>2</sup>	≤100 m	≤20 m

A = Actuator  
C = Control unit (controlling unit)  
L<sub>1</sub> = Connecting cable of the actuator  
L<sub>2</sub> = Customer cable  
L<sub>tot</sub> = Maximum signal cable length

**Note:**  
When several actuators are connected in parallel, the maximum signal cable length must be divided by the number of actuators.



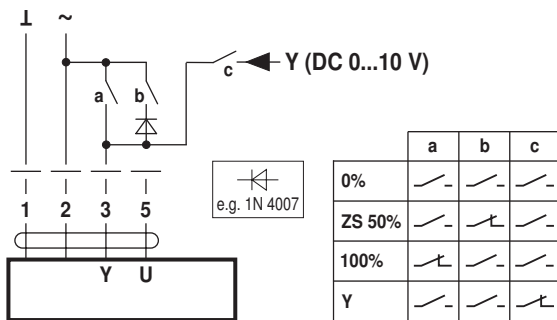
A = Actuator  
C = Control unit (controlling unit)  
L<sub>1</sub> = Connecting cable of the actuator

**Note:**  
There are no special restrictions on installation if the supply and the data cable are routed separately.

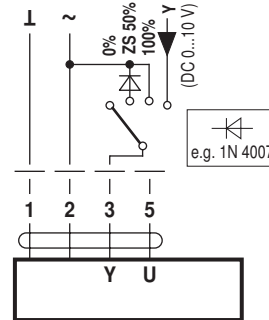
**Functions**

**Functions with basic values (conventional mode)**

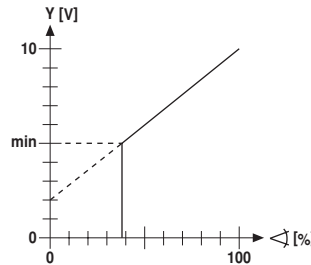
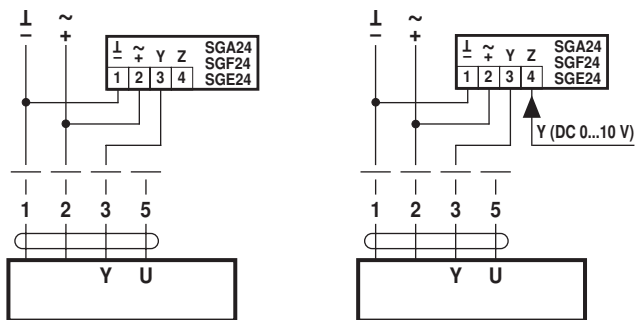
Override control with AC 24 V with relay contacts



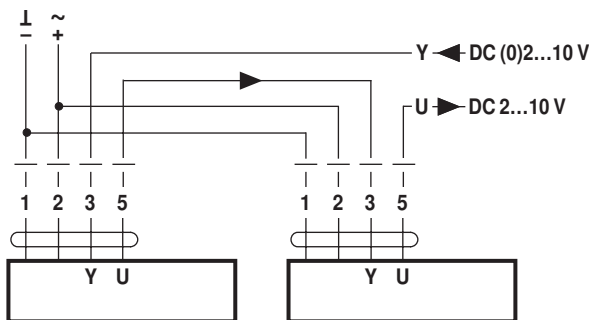
Override control with AC 24 V with rotary switch



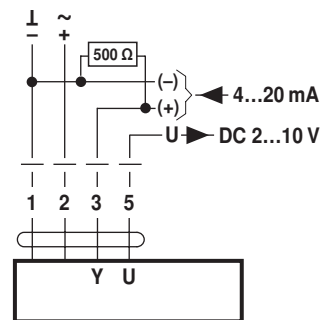
Control remotely 0...100% with positioner SG..  
positioner SG..



Follow-up control (position-dependent)

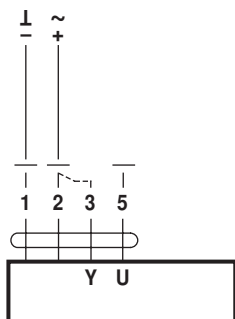


Control with 4...20 mA via external resistor



**Caution:**  
The operating range must be set to DC 2...10 V.  
The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

Functional check



**Procedure**

1. Connect 24V to connections 1 and 2
2. Disconnect connection 3:
  - with direction of rotation 0: Actuator rotates to the left
  - with direction of rotation 1: Actuator rotates to the right
3. Short-circuit connections 2 and 3:
  - Actuator runs in opposite direction

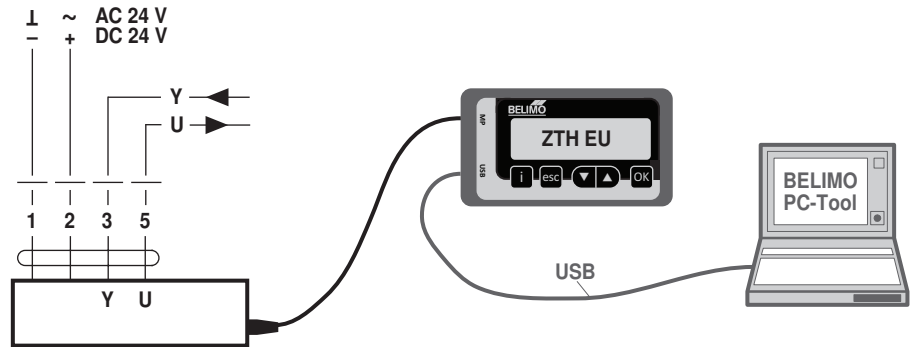


**Installation notes**

**Negative torque** Max. 50% of the torque (Caution: Application possible only with restrictions. Please contact your supplier.)

**Service**

**Service Tools connection** The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.  
Connection ZTH EU / PC-Tool



**Dimensions [mm]**

**Spindle length**

		Min. 42
		Min. 20

**Clamping range**

	8...26.7	≥8	≤26.7
	8...20	≥8	≤20

\*Option: Shaft clamp mounted below (accessory K-SA needed)

\*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.

**Dimensional drawings**

