

Communicative globe valve actuator for 2-way and 3-way globe valves

- Actuating force 1000 N
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Stroke 20 mm
- Conversion of sensor signals
- Communication via Belimo MP-Bus



NVC24A-MP-RE

RETRO FIT

Technical data

| Power consumption in operation S. V | | | |
|--|-----------------|---|-------------------------------------|
| Nominal voltage frequency Nominal voltage range AC 19.228.8 V / DC 21.628.8 V Power consumption in operation 3.5 W Power consumption in rest position 1.5 W Power consumption for wire sizing 5.5 VA Connection supply / control Parallel operation Yes (note the performance data) Functional data Actuating force motor Communicative control MP-Bus Operating range Y Input Impedance Operating range Y variable Start point 2.532 V Options positioning signal Options positioning signal Position feedback U Position feedback U variable Start point 0.58 V End point 2.53 V Position feedback U variable Start point 0.58 V End point 2.510 V Position feedback U variable Start point 0.58 V End point 2.510 V Position feedback U variable Start point 0.58 V End point 2.510 V Adaptation setting range Running time motor Stroke 20 mm Running time motor Running time motor Running time motor Adaptation setting range variable Override control MAX (maximum position) = 100% MIN (minimum position) = 100% MIN (minimum position) = 50% ZS (intermediate position, AC only) = 50% ZS (intermediate position, AC only) = 50% ZS (intermediate position, AC only) = 50% Size MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke | Electrical data | Nominal voltage | AC/DC 24 V |
| Nominal voltage range | | Nominal voltage frequency | 50/60 Hz |
| Power consumption in operation 3.5 W Power consumption in rest position 1.5 W Power consumption for wire sizing 5.5 VA Connection supply / control Terrminals 4 mm² (cable Ø410 mm) Parallel operation Yes (note the performance data) Functional data Actuating force motor 1000 N Communicative control MP-Bus Operating range Y 210 V Input Impedance 100 kΩ Operating range Y variable Start point 0.530 V End point 2.532 V End point 2.532 V Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U 210 V Position feedback U variable Start point 0.58 V End point 2.510 V End point 2.510 V Position accuracy 4.5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s./20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting ran | | | AC 19.228.8 V / DC 21.628.8 V |
| Power consumption for wire sizing S.5. VA Connection supply / control Terminals 4 mm² (cable Ø410 mm) | | Power consumption in operation | 3.5 W |
| Functional data Actuating force motor 1000 N Communicative control MP-Bus Operating range Y Input Impedance 100 KC Options positioning signal Open/close 3-point (Ac only) Modulating (DC 032 V) Position feedback U 210 V Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable 3590 s Adaptation setting range variable 3510 MAX (maximum position) = 100% Adaptation setting range motor wariable 3510 MAX (maximum position) = 0% ZS (intermediate position, AC only) = 50% MAX 0.5 mA Position accuracy 5 s / 20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting range manual (automatic on first power-up) Adaptation setting range ariable MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% MAX = (MIN + 33%)100% MIN = 9%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication III Safety Extra-Low Voltage (SELV) | | Power consumption in rest position | 1.5 W |
| Parallel operation Yes (note the performance data) Functional data Actuating force motor 1000 N Communicative control MP-Bus Operating range Y 210 V Input Impedance 100 kG Operating range Y variable Start point 0.530 V End point 2.532 V Options positioning signal Open/close 3-point (AC only) Position feedback U 0.210 V Position feedback U onte Max. 0.5 mA Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor 35 s / 20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting range wariable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN (minimum position) = 50% ZS = MINMAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication III Safety Extra-Low Voltage (SELV) | | Power consumption for wire sizing | 5.5 VA |
| Actuating force motor Communicative control Operating range Y Input Impedance Options positioning signal Options position feedback U Position feedback U note Position accuracy Manual override Storke Running time motor Running time motor variable Adaptation setting range Adaptation setting range Adaptation setting range Override control MAX (maximum position) = 0% ZS (intermediate position, AC only) = 50% MIN (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke Safety data | | Connection supply / control | Terminals 4 mm² (cable Ø410 mm) |
| Communicative control Operating range Y Input Impedance Operating range Y 210 V Input Impedance Operating range Y variable Start point 0.530 V End point 2.532 V Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U Position feedback U note Aday to sit on accuracy Position accuracy #5% Manual override Stroke 20 mm Running time motor Running time motor variable Adaptation setting range Adaptation setting range MAADA Adaptation setting range Adaptation setting range MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Parallel operation | Yes (note the performance data) |
| Operating range Y 210 V | Functional data | Actuating force motor | 1000 N |
| Input Impedance Operating range Y variable Operating range Y variable Start point 0.530 V End point 2.532 V Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override With push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor 35 s90 s Adaptation setting range Maptation setting range Maptation setting range Maptation setting range manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Communicative control | MP-Bus |
| Operating range Y variable Start point 0.530 V End point 2.532 V Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U 210 V Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override Stroke 20 mm Running time motor 35 s / 20 mm Running time motor ariable Adaptation setting range Adaptation setting range Adaptation setting range variable No action Adaptation when switched on Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke III Safety Extra-Low Voltage (SELV) | | Operating range Y | 210 V |
| End point 2.532 V Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U 210 V Position feedback U variable Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override With push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range Manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 00% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke | | Input Impedance | 100 kΩ |
| Options positioning signal Open/close 3-point (AC only) Modulating (DC 032 V) Position feedback U 210 V Position feedback U note Max. 0.5 mA Position feedback U variable Start point 2.510 V Position accuracy ±5% Manual override With push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range manual (automatic on first power-up) Adaptation setting range wariable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Forection class IEC/EN III Safety Extra-Low Voltage (SELV) | | - · - · · - · | Start point 0.530 V |
| 3-point (AC only) Modulating (DC 032 V) Position feedback U Position feedback U note Max. 0.5 mA Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override With push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range Madaptation setting range Modulating Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Frotection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | End point 2.532 V |
| Modulating (DC 032 V) Position feedback U 210 V Position feedback U note Max. 0.5 mA Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Frotection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Options positioning signal | • |
| Position feedback U Position feedback U note Position feedback U variable Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy \$\frac{\pmathbb{\text{5}}{\pmathbb{\text{5}}}}\$ Manual override With push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range Manual (automatic on first power-up) Adaptation setting range Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Frotection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | • |
| Position feedback U note Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range Mapual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation when switched on Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke | | - · · · · · · · · · · · · · · · · · · · | - |
| Position feedback U variable Start point 0.58 V End point 2.510 V Position accuracy ±5% Manual override Stroke Running time motor Running time motor variable Adaptation setting range Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| End point 2.510 V Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| Position accuracy ±5% Manual override with push-button, can be locked Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable 3590 s Adaptation setting range manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% Z5 (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) Z5 = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Position feedback U variable | • |
| Manual override Stroke 20 mm Running time motor 35 s / 20 mm Running time motor variable Adaptation setting range Adaptation setting range variable MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Position accuracy | · |
| Stroke Running time motor Running time motor variable Adaptation setting range Adaptation setting range variable Mo action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX Sound power level, motor Footion indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| Running time motor Running time motor variable Adaptation setting range Adaptation setting range variable Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | <u> </u> |
| Running time motor variable Adaptation setting range Adaptation setting range variable Adaptation setting range variable No action Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | <u> </u> |
| Adaptation setting range manual (automatic on first power-up) Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| Adaptation setting range variable No action Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | - | |
| Adaptation when switched on Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | <u> </u> |
| Adaptation after pushing the gear disengagement button Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Adaptation setting range variable | |
| Override control MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | · |
| MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | button |
| ZS (intermediate position, AC only) = 50% Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Override control | |
| Override control variable MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | • • |
| MIN = 0%(MAX - 33%) ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| ZS = MINMAX Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Override control variable | |
| Sound power level, motor 60 dB(A) Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | | |
| Position indication Mechanically, 520 mm stroke Safety data Protection class IEC/EN III Safety Extra-Low Voltage (SELV) | | Sound power level, motor | |
| | | | |
| | Safety data | Protection class IFC/FN | III Safety Extra-Low Voltage (SELV) |
| | Jaioty data | Protection class UL | UL Class 2 Supply |



| Technical data sheet | NVC24A-MP-RE |
|--|---|
| Degree of protection IEC/EN | IP54 |
| Degree of protection NEMA/UL | NEMA 2 |
| Enclosure | UL Enclosure Type 2 |
| EMC | CE according to 2014/30/EU |
| Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| Certification UL | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02 |
| Certification UL note | The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
| Mode of operation | Type 1 |
| Rated impulse voltage supply / control | 0.8 kV |
| Control pollution degree | 3 |
| Ambient temperature | 050°C |
| Storage temperature | -4080°C |
| Ambient humidity | Max. 95% r.H., non-condensing |
| Servicing | maintenance-free |
| Weight | 1.8 kg |

Safety notes



Weight

- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The switch for changing the direction of motion and so the closing point may be adjusted only by authorised specialists. The direction of motion is critical, particularly in connection with frost protection circuits.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The device contains electrical and electronic components and must not be disposed of as household
 refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

Conventional operation:

The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0.5...100% and as slave control signal for other actuators.

Operation on Bus:

The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Configurable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Mounting on third-party valves

The retrofit actuators for installation on a wide range of valves from various manufacturers are comprised of an actuator, bracket, universal valve neck adapter and universal valve stem adapter. Adapt the valve neck and valve stem to begin with, then attach the retrofit bracket to the valve neck adapter. Now fit the retrofit actuator into the bracket and connect it to the valve. Whilst taking the position of the valve closing



Technical data sheet

NVC24A-MP-RE

point into account, secure the actuator to the bracket and then conduct the commissioning process. The valve neck adapter/actuator can be rotated through 360° on the valve neck, provided it is permitted by the size of the installed valve.

Mounting on Belimo valves

Use standard actuators from Belimo for mounting on Belimo globe valves. The installation of retrofit actuators on Belimo globe valves is technically possible.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

The stroke can be adjusted by using a hexagon socket screw key (4 mm), which is inserted into the top of the actuator. The stroke shaft extends when the key is rotated clockwise.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Position indication

The stroke is indicated mechanically on the bracket with tabs. The stroke range adjusts itself automatically during operation.

Home position

Factory setting: Actuator spindle is retracted.

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.

The actuator then moves into the position defined by the positioning signal.

Adaptation and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both

mechanical end stops are detected during the adaption (entire setting range).

Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronization is in the home position (0%)

synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Setting direction of stroke

When actuated, the stroke direction switch changes the running direction in normal operation.

Accessories

| Gateways | Description | Туре |
|------------------------|---|----------------|
| | Gateway MP zu BACnet MS/TP | UK24BAC |
| | Gateway MP to KNX | UK24EIB |
| | Gateway MP to Modbus RTU | UK24MOD |
| Electrical accessories | Description | Туре |
| | | EXT-WR-FP20-MP |
| | Auxiliary switch 2 x SPDT add-on | S2A-H |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket | ZK1-GEN |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/ PP terminal | ZK2-GEN |
| | MP-Bus power supply for MP actuators | ZN230-24MP |
| Mechanical accessories | Description | Туре |
| | Spacer ring for LDM, stroke 20 mm | ZNV-203 |
| | Spacer ring for Sauter, stroke 20 mm | ZNV-204 |
| | Adapter kit Danfoss | ZNV-205 |
| Service tools | Description | Туре |
| | Adapter for Service-Tool ZTH | MFT-C |
| | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
| | Service Tool, with ZIP-USB function, for configurable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH EU |

Electrical installation



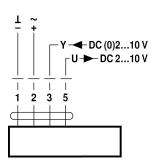
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data. Direction of stroke switch factory setting: Actuator spindle retracted (•).

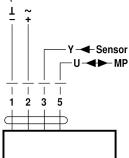


Wiring diagrams

AC/DC 24 V, modulating



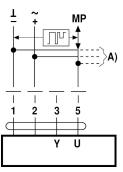
Operation on the MP-Bus

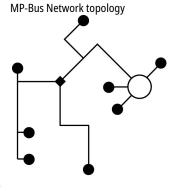


Functions

Functions when operated on MP-Bus

Connection on the MP-Bus

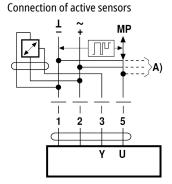




There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors required

.,



A) additional MP-Bus nodes (max. 8)

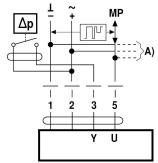
A) additional MP-Bus nodes (max. 8)

• Supply AC/DC 24 V

(max. DC 0...32 V)
• Resolution 30 mV

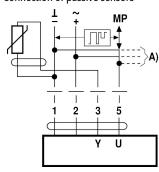
• Output signal DC 0...10 V

Connection of external switching contact



- A) additional MP-Bus nodes (max. 8)
- Switching current 16 mA @ 24 V
- Start point of the operating range must be parametrised on the MP actuator as ≥ 0.5 V

Connection of passive sensors



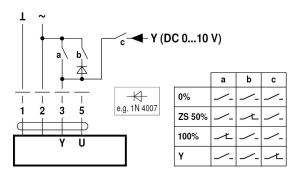
| Ni1000 | -28+98°C | 8501600 Ω ²⁾ |
|--------|--------------|--------------------------|
| PT1000 | −35+155°C | 8501600 Ω ²⁾ |
| NTC | -10+160°C 1) | 200 Ω60 kΩ ²⁾ |

- A) additional MP-Bus nodes (max. 8)
- 1) Depending on the type
- 2) Resolution 1 Ohm

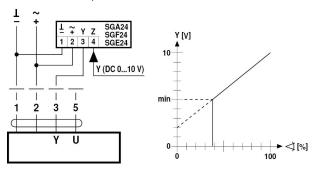


Functions with basic values (conventional mode)

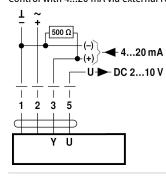
Override control with AC 24 V with relay contacts



Minimum limit with positioner SG..



Control with 4...20 mA via external resistor

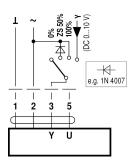


Caution:

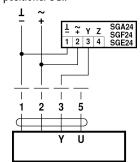
The operating range must be set to DC 2...10 V.

The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

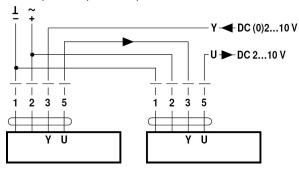
Override control with AC 24 V with rotary switch



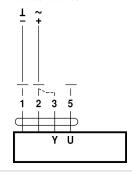
Control remotely 0...100% with positioner SG..



Follow-up control (position-dependent)



Functional check

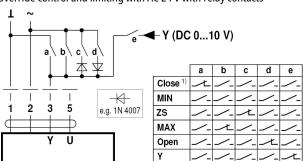


Procedure

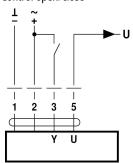
- 1. Apply 24 V to connection 1 and 2
- 2. Disconnect connection 3:
- with upwards direction of motion: closing point at top
- with downwards direction of motion: closing point at bottom
- 3. Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

Functions for actuators with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts

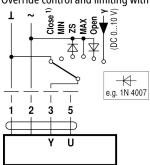


Control open/close



Control 3-point

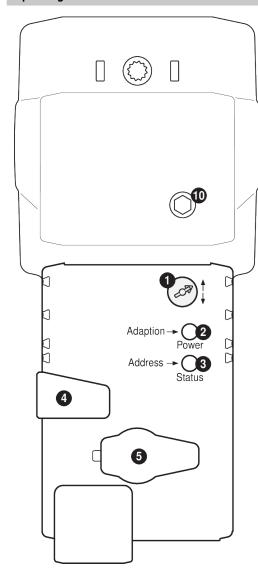
Override control and limiting with AC 24 V with rotary switch



1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.



Operating controls and indicators



Direction of stroke switch

Switch over: Direction of stroke changes

Push-button and LED display green

Off: No power supply or malfuntion

On: In operation

Press button: Triggers stroke adaptation, followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

Flickering: MP communication active On: Adaptation process active

Flashing: Request for addressing from MP master

Press button: Confirmation of the addressing

4 Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible

Release button: Gear engages, standard mode

5 Service plug

For connecting parameterisation and service tools

Manual override

Clockwise: Actuator spindle extends
Counterclockwise: Actuator spindle retracts

Check power supply connection

2 Off and 3 On Possible wiring error in power supply

Service

Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket.

For an extended parametrisation the PC tool can be connected.

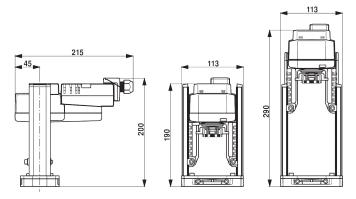
Connection ZTH EU / PC-Tool





Dimensions

Dimensional drawings



Further documentation

- Tool connections
- Introduction to MP-Bus Technology
- Overview MP Cooperation Partners
- Data sheets for globe valves
- Installation instructions for actuators