

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 4 m²
- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus





SM24A-MP



## **Technical data**

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Nominal voltage	AC/DC 24 V
Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	3.5 W
Power consumption in rest position	1.4 W
Power consumption for wire sizing	6 VA
Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>
Parallel operation	Yes (note the performance data)
Torque motor	20 Nm
Torque variable	25% 50% 75% reduced

## **Functional data**

Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>		
Parallel operation	Yes (note the performance data)		
Torque motor	20 Nm		
Torque variable	25%, 50%, 75% reduced		
Communicative control	MP-Bus		
Operating range Y	210 V		
Input Impedance	100 kΩ		
Operating range Y variable	Start point 0.530 V End point 2.532 V		
Options positioning signal	Open/close 3-point (AC only) Modulating (DC 032 V)		
Position feedback U	210 V		
Position feedback U note	Max. 0.5 mA		
Position feedback U variable	Start point 0.58 V End point 2.510 V		
Position accuracy	±5%		
Direction of motion motor	selectable with switch 0/1		
Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)		
Direction of motion variable	electronically reversible		
Manual override	with push-button, can be locked		
Angle of rotation	Max. 95°		
Angle of rotation note	can be limited on both sides with adjustable mechanical end stops		
Running time motor	150 s / 90°		
Running time motor variable	86346 s		
Adaptation setting range	manual		
Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the gear disengagement button		
Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%		



Technical data sheet	SM24A-MF
Override control variable	MAX = (MIN + 32%)100% MIN = 0%(MAX – 32%) ZS = MINMAX
Sound power level, motor	45 dB(A)
Mechanical interface	Universal shaft clamp reversible 1020 mm
Position indication	Mechanically, pluggable
Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
Protection class UL	UL Class 2 Supply
Degree of protection IEC/EN	IP54
Degree of protection NEMA/UL	NEMA 2
Enclosure	UL Enclosure Type 2
EMC	CE according to 2014/30/EU
Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
Certification UL	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02
Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
Mode of operation	Type 1
Rated impulse voltage supply / control	0.8 kV
Control pollution degree	3
Ambient temperature	-3050°C
Storage temperature	-4080°C
Ambient humidity	Max. 95% r.H., non-condensing
Servicing	maintenance-free

#### Safety notes



Weight

Weight

Safety data

The device must not be used outside the specified field of application, especially not in aircraft or in any
other airborne means of transport.

1.1 kg

- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases
  interfere directly with the device and that it is ensured that the ambient conditions remain within the
  thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

#### **Product features**

## Mode of operation

#### Conventional operation:

The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0.5...100% and as slave control signal for other actuators.

## Operation on Bus:

The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level

system.

**Configurable actuators** 

The factory settings cover the most common applications. Single parameters can be modified with the

Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation

device to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or

remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop

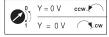
is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out the commission of the comm

a synchronisation. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.



**Adaptation and synchronisation** 

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both

mechanical end stops are detected during the adaption (entire setting range).

 $Automatic \ synchronisation \ after \ pressing \ the \ gearbox \ disengagement \ button \ is \ configured. \ The$ 

synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

#### **Accessories**

Gateways	Description	Туре
	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to KNX	UK24EIB
	Gateway MP to Modbus RTU	UK24MOD
Electrical accessories	Description	Туре
	Positioner for wall mounting	CRP24-B1
	•	EXT-WR-FP20-MP
	Feedback potentiometer 10 kΩ add-on	P10000A
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 2.8 kΩ add-on	P2800A
	Feedback potentiometer 5 kΩ add-on	P5000A
	Feedback potentiometer 500 Ω add-on	P500A
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Signal converter voltage/current 100 kΩ Supply AC/DC 24 V	Z-UIC
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	MP-Bus power supply for MP actuators	ZN230-24MP
Mechanical accessories	Description	Туре
	Angle of rotation limiter for K-NA and K-SA	20334-00001
	Actuator arm for standard shaft clamp (reversible)	AH-20
	Shaft extension 240 mm Ø20 mm for damper shaft Ø 1221 mm CrNi	AV12-25-I
	Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
	Shaft clamp one-sided, clamping range Ø826 mm, Multipack 20 pcs.	K-ENSA



# Technical data sheet SM24A-MP

Shaft clamp one-sided, clamping range Ø1226 mm, for CrNi shaft (INOX),	K-ENSA-I
Multipack 20 pcs.	
Shaft clamp reversible, clamping range Ø1020 mm	K-SA
Ball joint suitable for damper crank arm KH8 / KH10	KG10A
Ball joint suitable for damper crank arm KH8	KG8
Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180
Anti-rotation mechanism 230 mm, Multipack 20 pcs.	Z-ARS230
Position indicator, Multipack 20 pcs.	Z-PI
Base plate extension for SMA to SM/AM/SMD24R, pcs.	Z-SMA
Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-NSA
Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-NSA
Form fit insert 15x15 mm, Multipack 20 pcs.	ZF15-NSA
Form fit insert 16x16 mm, Multipack 20 pcs.	ZF16-NSA
Mounting kit for linkage operation for flat installation	ZG-SMA
Description	Туре
Adapter for Service-Tool ZTH	MFT-C
Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
Service Tool, with ZIP-USB function, for configurable and communicative Belimo	ZTH EU
actuators, VAV controller and HVAC performance devices	

#### **Electrical installation**



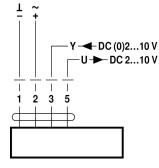
Service tools

Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

#### Wiring diagrams

AC/DC 24 V, modulating



Cable colours:

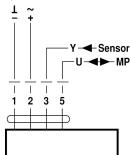
1 = black

2 = red

3 = white

5 = orange

## Operation on the MP-Bus



Cable colours:

1 = black

2 = red

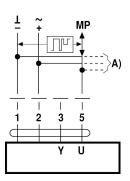
3 = white

5 = orange

#### **Functions**

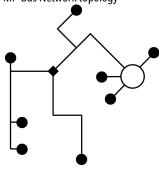
## Functions when operated on MP-Bus

Connection on the MP-Bus



A) additional MP-Bus nodes (max. 8)

## MP-Bus Network topology

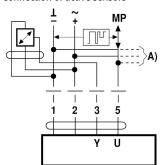


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors required



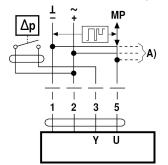
#### Connection of active sensors



A) additional MP-Bus nodes (max. 8)

- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

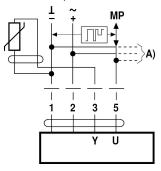
#### Connection of external switching contact



A) additional MP-Bus nodes (max. 8)

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parametrised on the MP actuator as  $\geq 0.5 \text{ V}$

#### Connection of passive sensors

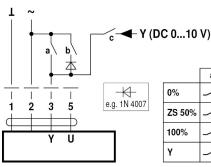


Ni1000	–28+98°C	8501600 Ω <sup>2)</sup>
PT1000	−35+155°C	8501600 Ω <sup>2)</sup>
NTC	-10+160°C 1)	200 Ω60 kΩ 2)

- A) additional MP-Bus nodes (max. 8)
- 1) Depending on the type
- 2) Resolution 1 Ohm

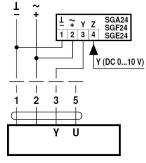
## Functions with basic values (conventional mode)

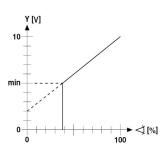
Override control with AC 24 V with relay contacts



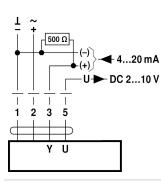
	а	b	С
0%	/-	/_	/-
ZS 50%	/_	Ł	/-
100%	Ł	/_	/-
Υ			Ł

Minimum limit with positioner SG..





Control with 4...20 mA via external resistor

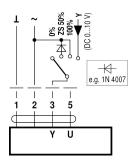


## Caution:

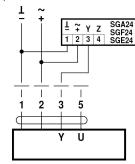
The operating range must be set to DC 2...10 V.

The 500  $\Omega$  resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

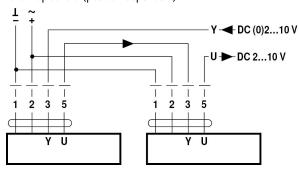
# Override control with AC 24 V with rotary switch



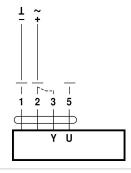
Control remotely 0...100% with positioner SG..



Follow-up control (position-dependent)



Functional check



## Procedure

- 1. Connect 24 V to connections 1 and 2
- 2. Disconnect connection 3:
- with direction of rotation 0:

Actuator rotates to the left

- with direction of rotation 1:

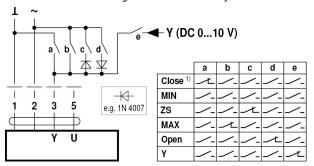
Actuator rotates to the right

- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

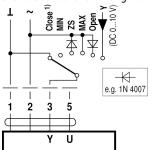


#### Functions for actuators with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts



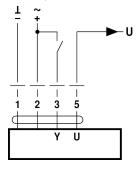
Override control and limiting with AC 24 V with rotary switch

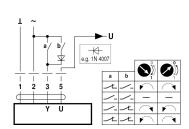


1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

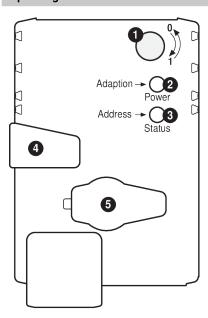
Control open/close

Control 3-point





## **Operating controls and indicators**



- Direction of rotation switch
  - Switch over: Direction of rotation changes
- 2 Push-button and LED display green

Off: No power supply or malfuntion

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

Flickering: MP communication active

On: Adaptation or synchronising process active Flashing: Request for addressing from MP master

Press button: Confirmation of the addressing

4 Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible

Release button: Gear engages, synchronisation starts, followed by standard mode

5 Service plug

For connecting parameterisation and service tools

## Check power supply connection

2 Off and 3 On Possible wiring error in power supply

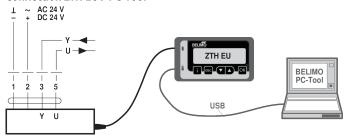
#### Service

**Service Tools connection** The actuator can be parametrised by ZTH EU via the service socket.

For an extended parametrisation the PC tool can be connected.

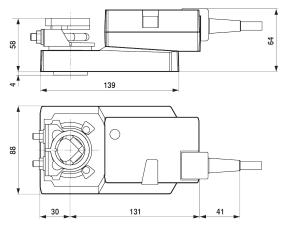


## Connection ZTH EU / PC-Tool



## **Dimensions**

## **Dimensional drawings**



Clamping range

	$\bigcirc$	<b>_</b>	<b>\]</b>
	1020	≥10	≤20
CrNi (INOX)	1220	≥10	≤20

When using a round spindle made of CrNi (INOX): Ø 12...20 mm

# Shaft length





Min. 48

Min. 20

## **Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology

## **Application notes**

 $\bullet$  For digital control of actuators in VAV applications patent EP 3163399 must be considered.