

VAV-Universal, modular control solution with integrated  $\Delta p$  sensor. Can be combined with damper actuator optimally suited to the VAV/ pressure duct application. Field of application: technical building equipment, HVAC systems

- Application: VAV/CAV units or duct pressure control in the comfort area
- Functional range differential pressure 0...500 Pa
- suitable for ...-VST actuator
- Control modulating, communicative, hybrid

• Communication via BACnet MS/TP, Modbus RTU, Belimo MP-Bus or conventional control

# **Technical data**



**Technical data sheet** 



Electrical data	Nominal voltage	AC/DC 24 V						
	Nominal voltage frequency	50/60 Hz						
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V						
	Power consumption in operation	1.5 W						
	Power consumption for wire sizing	2 VA plus connected VST actuator						
	Power consumption for wire sizing note	Imax 20 A @ 5 ms						
	Connection supply / control	Terminals 2.5 mm <sup>2</sup>						
	Sensor input S1	Connection of external sensor (passive / active / switch)						
	Actuator Connection (I) (M)	AC/DC 24 V, PP-Link for VST actuator						
Functional data	Communicative control	BACnet MS/TP Modbus RTU MP-Bus						
	Operating range Y	210 V						
	Input Impedance	100 kΩ						
	Operating range Y variable	0.510 V						
	Position feedback U note	Max. 0.5 mA Options: Volume / Δp / Position						
	Position feedback U variable	010 V Start point 08 V End point 210 V						
	Override control	z1 motor stop / damper OPEN (AC/DC 24 V) z2 damper CLOSE / MAX (AC/DC 24 V)						
	Parametrisation	via Belimo Assistant App / PC-Tool						
Measuring data	Measuring principle	Belimo D3, flow through sensor (dynamic measurement)						
	Installation position	position-independent, no zeroing necessary						
	Measuring range pressure	-20500 Pa						
	Functional range differential pressure	0500 Pa						
	Accuracy differential pressure	±1 Pa @ 020 Pa ±5% @ 20500 Pa						
	Maximum System pressure	1500 Pa						
	Pipe influence	max. +2.5%, linear value for 20 m hose length (5 mn inner diameter) on duct pressure control (STP)						
	Burst pressure	±10 kPa						
	Height compensation	Adjustment of system height (range 03000 m above sea level)						
	Condition measuring air	050°C / 595% RH, non-condensing						
	Pressure hose connection	Nipple diameter 5.3 mm max. 20 m pressure hose length (5 mm inner diameter) for duct pressure control (STP)						



Safety data	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)				
	Degree of protection IEC/EN	IP42				
	EMC	CE according to 2014/30/EU				
	Certification IEC/EN	IEC/EN 60730-1				
	Mode of operation	Туре 1				
	Rated impulse voltage supply / control	0.8 kV				
	Control pollution degree	2				
	Ambient temperature	050°C				
	Storage temperature	-2080°C				
	Ambient humidity	Max. 95% r.H., non-condensing				
	Servicing	maintenance-free				
Weight	Weight	0.30 kg				

- other airborne means of transport.
   Outdoor applications: only possible if no (sea) water, snow, ice, solar radiation and aggressive gases act directly on the device, and it is guaranteed that the ambient conditions are always within the limit values
  - according to the data sheet.
    Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
  - The device may only be opened by lifting the cover. It does not contain any parts that can be replaced or repaired by the user.
  - The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

**Product features** 

Safety notes

The VAV universal controller VRU-D3-BAC is used in the comfort area for pressure-independent control of Application VAV units, for recording a volume flow or for controlling duct pressure. See application library for description. Pressure measurement The integrated D3 differential pressure sensor is also suitable for very small volume flows. The maintenance-free sensor technology enables a wide range of applications in the HVAC comfort area: residential construction, office, hotel, etc. Actuators For the various applications and damper designs, the VAV unit manufacturer has various actuator variants with running times of 2.5 ... 120 s available. **Control functions** Volume flow (VAV/CAV), duct pressure (STP) or Position Control (Open-Loop) Application Variable Volume flow rate (VAV) Variable volume flow control in the V'min...V'max range, demand-dependent via a modulating reference variable (analogue or bus), e.g. room temperature, CO2 controller for energy-saving air conditioning of individual rooms or zones. V'nom, Δp @ V'nom OEM specific calibration parameters, suitable for the VAV unit Setting range  $\Delta p @ V'nom: 38...500 Pa$ V'max / Max Maximum operating volume flow, adjustable 20...100% V'nom V'min / Min Minimum operating volume flow, adjustable 0...100% V'nom



Technical data sheet

Application Constant Volume flow rate (CAV)	Constant volume flow control. If required, via step switching (switching contacts) for constant volume flow applications.
	Steps: CLOSE / Min / Max / OPEN
Application Volumetric flow measurement	Measurement of a volumetric flow, e.g. for summation or as setpoint measurement for a common extract air box. Transmitter, without damper actuator
	V'nom, Δp @ V'nom
	OEM-specific calibration parameters, suitable for the measuring device
	Setting range Δp @ V'nom: 38500 Pa
Application Position Control (Open-Loop)	Position Control for integration of the VRUBAC into an external VAV control loop. Transmitter and actuator unit.
	Max
	Range: 20100 % rotation range
	Min
	Range: 0100 % rotation range
Application duct pressure (STP)	Channel or strand pressure control in step operation (switching contacts): CLOSE / P'min / P'max or variable specification of the Δp value P'minP'max via a continuous command variable (analogue or bus). Lower control limit (STP) 38 Pa
	P'nom OEM specific calibration parameters: 38500 Pa
	P'max
	P max Maximum operating pressure, adjustable 20100% P'nom
	P'min
	Minimum operating pressure, adjustable 0100% P'nom
Demand Control Ventilation (DCV)	Output of the demand signal (damper position) to the higher-level automation system - DCV function (Fan Optimizer).
Bus operation	Thanks to the multi-bus functionality of the VRUBAC, the VAV universal controllers can be easily integrated into a bus system. The communication interface is defined on the system using the Belimo Assistant App: BACnet MS/TP, Modbus RTU, Belimo MP-Bus.
	A hybrid mode is optionally available for BACnet MS/TP and Modbus RTU, bus connection combined with analogue control.
	In bus mode, a sensor (010 V / passive) can optionally be connected, e.g. a temperature sensor or a switching contact, for integration into the higher-level bus system.
MP-Bus application Compatibility mode:	The VRUBAC is based on the new Belimo MP data pool model.
Standard / VRP-M	If the VRUBAC is used as a VRP-M replacement in an existing MP-Bus system, the VRUBAC can be set to the VRP-M function with the compatibility mode parameter. See instructions: VAV-Universal - MP-Bus Existing system: Replace VRP-M with VRUBAC.
Operating settings	Control functions
	Volume flow (VAV/CAV), duct pressure (STP - lower control limit 38 Pa) or Position Control (Open-Loop)
	Operating settings Min / Max / Nominal
	$\mathbf{\hat{f}}$
Nominal value (OEM setting) Nom	1 2
Nominal value (OEM setting) Nom Setting range Min 1	
Setting range Max 2	20%
Feedback U 0100% Nom 3 Control Y MinMax 4	0% ¥ 4
Cond of Fiviniwdx 4	



# Technical data sheet

Operating and service tools Smartphone with Belimo Assistant App - contactless operation via the integrated NFC interface. PC-Tool (ZTH EU) - can be locally plugged into the service socket or remotely via MP connection.

Service to	ls Description	Туре
	Belimo Assistant App, Smartphone app for easy commissioning, parametrising	Belimo Assistant
	and maintenance	Арр
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Converter Bluetooth / NFC	ZIP-BT-NFC
	Service Tool, with ZIP-USB function, for parametrisable and communicative	ZTH EU
	Belimo actuators, VAV controller and HVAC performance devices	
	Complete functions ZIP-BT-NFC as of production date 2019-10-15	

# **Electrical installation**



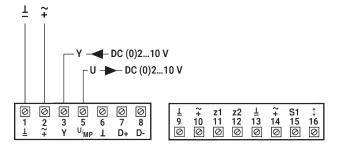
#### Supply from isolating transformer.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable **RS485 regulations.** 

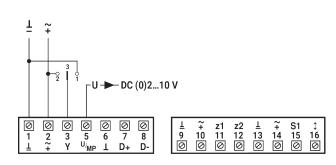
Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

# Wiring diagrams

AC/DC 24 V, modulating (VAV)



#### AC/DC 24 V, contactor step control (CAV)



# AC/DC 24 V, override control z1/z2 0

0 0

5 6 <sup>U/</sup>MP 1

0 0

2 3 Y

0

11110121722							
Ø Ø 7 8 D+ D-	⊥ 9 ⊘	∓ 10 ⊘	z1 11 ⊘	z2 12 Ø	⊥ 13 ⊘	∓ 14 ⊘	S1 15 Ø
			9 0	14	13 2		

#### Priority rule - Analog VAV control (a)

- 1. z1
- 2. z2
- 3. a) adaptation
- b) synchronisation
- 4. Y-modulating: min...max

(see override control z1/z2)

# Priority rule - Analogue CAV step

- control (b) 1. z1
- 2. z2
- 3. a) adaptation
- b) synchronisation
- 4. Y-steps: CLOSE-MIN-MAX

(see override comtrol z1/z2)

Contact 2-3 = MAX 3 uncoated = MIN Contact 1-3 = CLOSE (mode 2...10 V) MIN (mode 0...10 V)

# **Override control z1**

Contact 11-9 = Motor STOP Contact 11-10 = Damper OPEN

#### Override control z2

Contact 12-13 = Damper CLOSED Contact 12-14 = MAX

11/12 uncoated = priority rule a/b/c/d/e

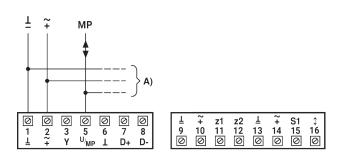
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0

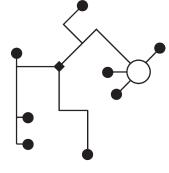


# Functions for actuators with specific parameters (NFC)

MP-Bus

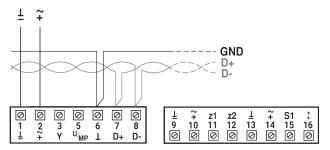


# MP-Bus Network topology

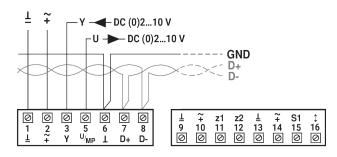


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary • no terminating resistors required

### BACnet MS/TP / Modbus RTU



BACnet MS/TP / Modbus RTU with analog setpoint (hybrid mode)



# Priority rule MP-Bus control (c)

- 1. z1
- 2. z2
- 3. Bus watchdog
- 4. a) adaptation
- b) synchronisation
- 5. Y-step: actuator CLOSED / MIN /
- MAX
- 6. Bus override
- 7. Bus setpoint: min...max
- A) additional MP-Bus nodes (max. 8)

Priority rule BACnet/Modbus

- control (d)
- 1. z1
- 2. z2
- 3. Bus watchdog
- 4. a) adaptation b) synchronisation
- 5. Bus override
- 6. Bus setpoint: min...max

# Priority rule BACnet/Modbus hybrid mode (e)

- 1. z1
- 2. z2
- 3. Bus watchdog
- 4. a) adaptation
- b) synchronisation
- 5. Bus override
- 6. Y-step: actuator CLOSE / MIN /
- MAX
- 7. Bus setpoint: min...max



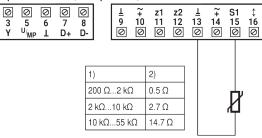
Ø 2 ~

3 Y

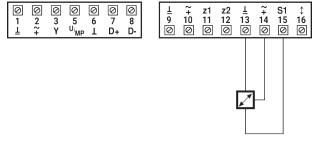
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1

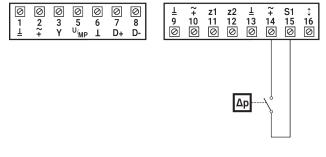
### Connection passive sensor (bus operation)



# Connection of active sensor (bus operation)



### Connection switching contact (bus operation)



1) Resistance range 2) Resolution Suitable for Ni1000 and Pt1000 Corresponding Belimo sensors 01DT-..

Possible input voltage range: DC 0...10 V (resolution 5 mV) Example:

- Active temperature sensors

- setpoint generator

- humidity sensor

Requirements switching contact: The switch must be capable of switching a current of 10 mA @ 24 V cleanly. Example: - dP sensor

- window contact

#### Parameter and tool overview



			Appli	Application			Тооі			Authori- sation	
Parameter/function	Unit/value	Function/description/(area)	VAV/CAV	Vol. measure- ment	Position control	Air duct pressure	Assistant app	PC-Tool	ZTHEU	Expert/OEM	
Overview											
Position	String	– Plant designation (64 Z./ZTH 10 Z.)	Х	Х	Х	Х	r	r	r		
Series number		Series number VRU	X	X	X	X	r	r	r		
Voltage source	24 V/-		X	X	X	X	r		·		
Туре	VRU-D3-BAC		X	X	Х	X	r	r	r		
Application	- Volumetric flow - Measure volumetric flow - Air duct pressure	Application setting (OEM setting)	×××	X	Х	X	r	r	r		
Control function	VAV-CAV/Position control	Control function (OEM setting)	X		Х		r	r	r		
Designation	String	Model designation unit/damper (OEM,16 Z.)	X	X	Х	X	r	r	_		
Setpoint	VAV: m³/h / l/s / cfm (ZTH: %) Position: % Δp: Pa (ZTH: %)	Display live data dependent on the selected application	×	_	X	X	X	×	×		
Actual value	VAV: m <sup>3</sup> /h / l/s / cfm (ZTH: %) Position: % Δp: Pa (ZTH: %)	Display live data dependent on the selected application	×	X	Х	X	X	X	X		
Damper position	0100%	Live data display	X		Х	X	Х	X	X		
Override control	Auto/MIN/MAX / OPEN/CLOSE/Motor stop/ Nom	Temporary override function (Tool override)	×		Х	X	X	X			
Actuator	Adaption, synchronisation	 Trigger adaption, synchronisation	X		Х	X	X	X		E	
Transmit setting data		System documentation	X	X	X	X	X	X			
Save setting data		Save setting in file	X	Х	Х	Х		Х			
Trend display	Setpoint, actual value, damper position	Commissioning, validation, service	X		Х	X	×	×			
Trend display	Actual value (volumetric flow)	Commissioning, validation, service		Х			Х	Х			
Transmit trend data		Commissioning, validation, service	Х	Х	Х	Х	Х	Х			
Diagnosis – Evaluation	Status										
Actuator	OK/Gear disengaged/Actuator nected actuator does not mate	blocked/Setting range extended/Con- h the application	×		Х	Х	Х				
Sensor	$OK/\Delta p$ sensor incorrectly conr measuring range/ $\Delta p$ sensor er	ected/measuring value outside ror	×	X	Х	Х	Х				
Volumetric flow/air duct pressure	OK/Setpoint not reached		×	X	Х	X	X				
Bus	OK/Bus watchdog triggered		X	Х	Х	Х	Х				
Diagnosis – Installation	Unit/value	Function/description/(area)									
Voltage source	24 V/deenergised		X	X	Х	X	X				
Operating time	h	Device connected to supply	X	X	Х	Х	_X				

Availability: VAV-Universal components incl. replacement devices are only available from manufacturers of VAV units (OEM). Authorisations: [E-Expert Level] - Functionally relevant settings are only

accessible via the Expert Level of the Belimo Assistant App.

#### Legend Х

Application supports function/parameter

r

W

Tool: read Tool: write Tool: Does not support parameter

Е Only visible in Expert Mode



# **Parametrisation**

Parameter/function         UnitValue         Panction/description/area)         V         V         V         V         V         V           Application         -Volumetric flow         Application setting         -         -         -         0           Application         -Volumetric flow         Application setting         -         -         -         0           Designation         -Volumetric flow         Model designation unit/demper (16 2)         X         X         X         -         r         r         0           Vnom         mYh / I/s / cfm         Wolumetric flow nominal value         X         X         X         X         X         -         r         r         0           Ange of rotation         Adapter/one         Pa         Calibration VAV unit (18: 600 Pa)         X         X         X         X         X         x         x         r         r         0           Statuard         Exclusor direction of rotation setting         X				Appl	ication			Tool			Authori- sation
Application       - Volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow nominal value X nom       r </th <th>Parameter/function</th> <th>Unit/value</th> <th>Function/description/(area)</th> <th>VAV/CAV</th> <th>Vol. measure- ment</th> <th>Position control</th> <th>Air duct pressure</th> <th>Assistant app</th> <th>PC-Tool</th> <th>ZTH EU</th> <th>Expert/OEM</th>	Parameter/function	Unit/value	Function/description/(area)	VAV/CAV	Vol. measure- ment	Position control	Air duct pressure	Assistant app	PC-Tool	ZTH EU	Expert/OEM
Application       - Volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow Measure volumetric flow nominal value X nom       r </td <td>VAV unit/Air duct pressure c</td> <td>ontrol hutterfly valve - manufacture</td> <td>r parameters (OFM values - not variable)</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>	VAV unit/Air duct pressure c	ontrol hutterfly valve - manufacture	r parameters (OFM values - not variable)								
Vinom         mVh / I/s / cfm         Volumetric flow nominal value         X         X         X         T         r         0         O         Columbra         Columbra <td></td> <td>- Volumetric flow - Measure volumetric flow</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>r</td> <td>r</td> <td>r</td> <td>0</td>		- Volumetric flow - Measure volumetric flow						r	r	r	0
VinommYh / I/s / cfmVolumetric flow nominal valuexxxxxrrr <thr>ConstructureS&lt;</thr>	Designation	Text string	Model designation unit/damper (16 Z.)	X	X	X	X	r	r	_	0
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	V'nom	m <sup>3</sup> /h / l/s / cfm	Volumetric flow nominal value	_				r	r	r	
Pinom       Pa       Nominal value Δp STP [38.:500 Pa]       Image: String st	Δp@V'nom	Pa	Calibration VAV unit [38500 Pa]	_				r	r	_	
SN Actuator       xxxxx xxxx xxxx       Actuator series number       X       X       X       X       Y       X       Y       Y       Y       -       E         Ratation Direction       CCW/CW       Actuator direction of rotation setting       X       X       X       Y       Y       Y       Y       Y       -       E         Range of rotation       Adapted/programmed actuator adapted/programmed actuator power on behaviour       X       X       X       Y       Y       r/w       -       E         Suppress damper leakage       OFF/ON       Retrofit application, damper leakage leakage       X							- <u> </u>	r	r	r	
Rotation Direction       CCW/CW       Actuator direction of rotation setting       X       X       X       Y				X		X		 r	· <u>·</u>		5
Range of rotation       Adapted/programmed       Actuator adapted/programmed       X       X       X       X       X       Y	Rotation Direction								r/w	_	F
AdaptionXXXXXT/WT/W-ESuppress damper leakageOFF/ONRetrofit application, damper leakageXXXXXrrrr-0NFC interfaceON/OFFNFC Communication for app accessXXXXXXrrr-0Parametrisation - Project-specific settingsPositionText stringPlant designation (64 Z / ZTH 16 Z)XXXXr/Wr/Wr/WrMaxm <sup>0</sup> /h / I/s / cfm (PC-Tool / ZTH %) Pa (PC-Tool / ZTH %) Pa (PC-Tool / ZTH %)Operating volumetric flow 0100% Vnom Damper position (Pos.Cntrl.) 20100% Vnom Meg (Position)XXXXxr/Wr/Wr/WMinm <sup>0</sup> /h / I/s / cfm (PC-Tool / ZTH %) Pa (PC-Tool / ZTH %) Pa (PC-Tool / ZTH %) Pa per prion 0100% Phom Pa (PC-Tool / ZTH %) Mapstep max 20100% Phom Pa (PC-Tool / ZTH %) Mapstep min 0100% Phom Pa (PC-Tool / ZTH %)XXXXxr/Wr/Wr/Wr/WAltitude compensationON/OFFXXXXXXxxr/Wr/Wr/W-EFunctionVAV-CAV/Position controlControl functionControl functionXXXXXr/Wr/W-EFunctionVAV-CAV/Position controlControl functionXXXXXr/Wr/W </td <td>Range of rotation</td> <td>Adapted/programmed</td> <td>Actuator adapted/programmed</td> <td>_</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>_</td> <td></td>	Range of rotation	Adapted/programmed	Actuator adapted/programmed	_						_	
leakage       x </td <td>Power on behaviour</td> <td>-</td> <td>Actuator power on behaviour</td> <td>Х</td> <td></td> <td>Х</td> <td>X</td> <td>r/w</td> <td>r/w</td> <td>_</td> <td>E</td>	Power on behaviour	-	Actuator power on behaviour	Х		Х	X	r/w	r/w	_	E
Parametrisation - Project-specific settings       Plant designation (64 Z./ZTH 16 Z.)       X		OFF/ON	Retrofit application, damper leakage	Х				r	r	_	0
PositionText stringPlant designation (64 Z./ZTH 16 Z.)XXXXXYr/wr/wrMaxm³/h / I/s / cfm (PC-Tool / ZTH %) % (Position) Pa (PC-Tool/ZTH %) (PC-Tool/ZTH %)Operating volumetric flow 20100% Vnom Damper position (Pos.Cntrl.) 20100% VnomXXXXXr/wr/wr/wr/wrMinm³/h / I/s / cfm (PC-Tool/ZTH %) % (Position) Pa (PC-Tool/ZTH %) Me step max 20100% PhomOperating volumetric flow 0100% Vnom 	NFC interface	ON/OFF	NFC Communication for app access	Х	Х	Х	Х	r	r	_	0
PositionText stringPlant designation (64 Z./ZTH 16 Z.)XXXXXr/wr/wrMaxm³/h / I/s / cfm (PC-Tool / ZTH %) % (Position) Pa (PC-Tool/ZTH %) (PC-Tool/ZTH %)Operating volumetric flow 20100% Vnom Damper position (Pos.Cntrl.) 20100% VnomXXXXxr/wr/wr/wrMinm³/h / I/s / cfm (PC-Tool/ZTH %) % (Position) Pa (PC-Tool/ZTH %) % (Position) Pa (PC-Tool/ZTH %) Pa (PC-Tool/ZTH %) Ap step min 0100% P'nomXXXXxr/wr/wr/wr/wAltitude compensation ON/OFFON/OFFSwitch function ON/OFFFXXXXxr/wr/w-EFunctionON/OFFOmCompensated Δp and volumetric flow values to set the altitude of installation (above sea level)XXXXXr/wr/w-EFunctionVAV-CAV/Position controlControl functionXXXXXr/wr/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXXr/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXXXXXr/wr/w-EEductionVAV: ±5% compensation ABL unitXXXXXr/wr/w-EEductionVAV: ±5% compensation ABL unitXXXX	Parametrisation – Project-si	pecific settings		_							
Maxm³/h / l/s / cfm (PC-Tool / ZTH %) % (Position) Pa (PC-Tool/ZTH %) % (Position) Pa (PC-Tool/ZTH %)Operating volumetric flow 20100% Vinom Damper position (Pos.Cntrl.) 20100% Ap step max 20100% P'nomXXXXXr/wr/wr/wMinm³/h / l/s / cfm (PC-Tool/ZTH %) % (Position) Pa (PC-Tool/ZTH %) Pa (PC-Tool/ZTH %)Operating volumetric flow 0100% Vinom Damper position (Pos.Cntrl.) 0100% Vinom Damper position (Pos.Cntrl.) 0100% Ap step min 0100% P'nomXXXXXr/wr/wr/wr/wAltitude compensation Altitude of installation ControlON/OFFXXXXXXr/wr/w-EFunctionVAV-CAV/Position controlControl function Control functionXXXXXr/wr/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXXr/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXXXXXr/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXXr/wr/w-EEquationVAV: Solution controlVAV: tolwe/dp/Damper positionXXXXXr/w-EEnderSetpointAnalogue/busAnalogue and hybrid mode/busXXXXX <td></td> <td></td> <td>Plant designation (64.7 /7TH 16.7 )</td> <td>V</td> <td>V</td> <td>V</td> <td>V</td> <td>r/w</td> <td>r/w</td> <td>r</td> <td></td>			Plant designation (64.7 /7TH 16.7 )	V	V	V	V	r/w	r/w	r	
Minm³/h / I/s / cfm (PC-TooI/ZTH %) % (Position) Pa (PC-TooI/ZTH %) % (Position) Pa (PC-TooI/ZTH %)Operating volumetric flow 0100% V'nom Damper position (Pos.Cntrl.) 0100% Δp step min 0100% P'nomXXXXXxx		m <sup>3</sup> /h / l/s / cfm (PC-Tool / ZTH %) % (Position)	Operating volumetric flow 20100% V'nom Damper position (Pos.Cntrl.) 20100%								
Altitude of installationOmcompensated Δp and volumetric flow values to set the altitude of installation (above sea level)XXXXXXr/wr/w-EFunctionVAV-CAV/Position controlControl functionXXXXXr/wr/w-ERoom pressure cascadeOFF/ONVAV: Secondary circuit room pressure cascadeXXXXXr/wr/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXXr/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXXXXr/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Min	(PC-Tool/ZTH %) % (Position)	V'nom Damper position (Pos.Cntrl.) 0100%	×	X	Х	X	r/w	r/w	r/w	
Values to set the altitude of installation (above sea level)XXXXXXY/wr/w-EFunctionVAV-CAV/Position controlControl functionXXXXY/wr/w-ERoom pressure cascadeOFF/ONVAV: Secondary circuit room pressure cascadeXXXXXY/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXY/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXXXXY/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXY/wr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionXXXXXY/w-E	Altitude compensation	ON/OFF	Switch function ON/OFF	Х	Х	Х	Х	r/w	r/w	_	Е
Room pressure cascadeOFF/ONVAV: Secondary circuit room pressure cascadeXVr/wr/wr/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXXr/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXXXXYr/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Altitude of installation	0m	values to set the altitude of installation	Х	Х	Х	Х	r/w	r/w	_	E
Room pressure cascadeOFF/ONVAV: Secondary circuit room pressure cascadeXII/wr/wr/w-ESetpointAnalogue/busAnalogue and hybrid mode/busXXXXXr/wr/w-ESetpoint offset0%VAV: ±5% compensation ABL unitXIIr/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Function	VAV-CAV/Position control	Control function	Х		Х		r/w	r/w	_	E
Setpoint offset0%VAV: ±5% compensation ABL unitXIr/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Room pressure cascade	OFF/ON								_	
Setpoint offset0%VAV: ±5% compensation ABL unitXIIF/wr/w-EReference signal Y210 V/010 V/adjustableSetting for VAV controlXXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Setpoint	Analogue/bus	Analogue and hybrid mode/bus	Х	X	Х	X	r/w	r/w	_	E
Reference signal Y210 V/010 V/adjustableSetting for VAV controlXXXr/wr/w-EFeedback typeVolumetric flow/Δp/PositionVAV: Volume/Δp/Damper positionX(X)XXr/wr/w-E	Setpoint offset	0%	VAV: ±5% compensation ABL unit							_	
Feedback type       Volumetric flow/Δp/Position       VAV: Volume/Δp/Damper position       X       (X)       X       x       r/w       r/w       -       E	Reference signal Y	210 V/010 V/adjustable	Setting for VAV control			Х	X			_	
	Feedback type				(X)					_	
	Feedback U	210 V/010 V/adjustable	Setting U signal	Х	Х	Х		r/w	r/w	_	E

Availability: VAV-Universal components incl. replacement devices are only available from manufacturers of VAV units (OEM).

Authorisations: [E-Expert Level] - Functionally relevant settings are only

accessible via the Expert Level of the Belimo Assistant App.

#### Legend

Application supports function/parameter Tool: read Х

r W Tool: write

Tool: Does not support parameter Only visible in Expert Mode Е



# **Bus parameter**

				Tool				
Parameter/function	Unit/value	Function/description/(area)	Assistant app	PC-Tool	ZTH EU	Expert/OEM		
Parametrisation – Commu	inication							
Bus protocol	BACnet MS/TP / Modbus / MP	_	r/w	_	_	E		
Bus protocol	BACnet MS/TP							
MAC address	0127		r/w	_	_	Е		
Baudrate	9600 / / 115200		r/w	_	_	Е		
Terminating resistor	OFF/ON		r/w	_	_	Е		
Instance number	14194304		r/w	_	_	Е		
Device Name	VAV Universal	(32 Z.)	r/w	-	_	Е		
Max master	0127		r/w	_	_	E		
Bus protocol	Modbus RTU							
Address	1247		r/w	_	-	E		
Baudrate	9600 / / 115200		r/w	_	_	Е		
Terminating resistor	OFF/ON		r/w	_	_	Е		
Parity	1-8-N-2/E-1/0-1/N-1		r/w	_	_	E		
Bus protocol	MP-Bus							
MP Address	 PP/MP18	PP (MP off)/MP18	r/w	r/w	_	E		
Bus fail position	0%	0100% (minmax)	r/w	_	_	Е		
Compatibility mode	Default/VRP-M <sup>1)</sup>	Default: Belimo MP datapool device VRP-M: VRP-M replacement in existing MP system <sup>1)</sup>	r/w	r/w	_	E		

#### Note:

<sup>1)</sup> Refer to instructions: VAV-Universal - MP-Bus existing system: Replace VRP-M with VRU-...-BAC

#### Availability:

VAV-Universal components incl. replacement devices are only available from manufacturers of VAV units (OEM).

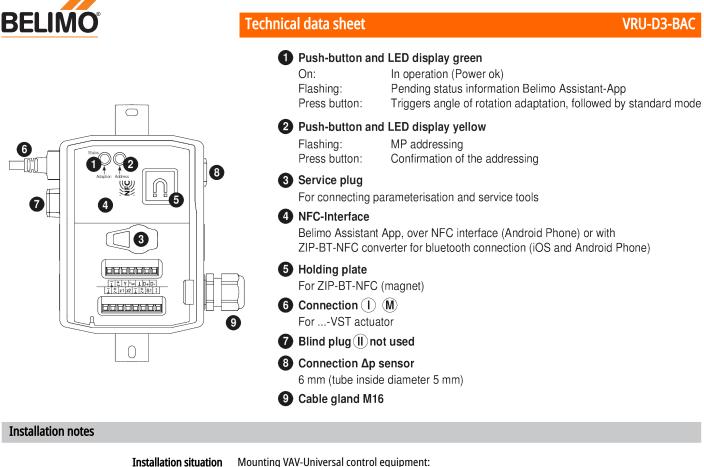
## Authorisations:

[O-OEM, Manufacturer Level] - VRU controllers are calibrated and parameterised by the unit manufacturer according to the application and project. These settings can only be changed by the manufacturer. [E-Expert Level] - Functionally relevant settings are only accessible via the Expert Level of the Belimo Assistant App.

## **Operating controls and indicators**

## Legend:

- X Application supports function/parameter
- Tool: read w Tool: write
- Tool: Does not support parameter
- O Access only with OEM authorisation
- E Only visible in Expert Mode



Mounting VAV-Universal control equipment:

The VAV-Universal set is assembled on the VAV unit in factory by the VAV unit manufacturer, the actuator connected to the VRU controller, set and calibrated.

Installation of the VAV unit:

The VAV unit must be installed according to the specifications of the VAV unit manufacturer.

Installation specification  $\Delta p$  sensor:

No restrictions, but it must be avoided that any condensation can run into the sensor and remain there.

Accessibility of control equipment:

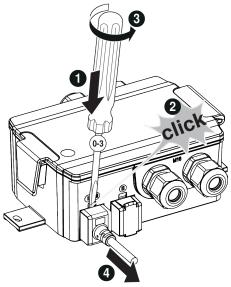
Accessibility to the control equipment must be guaranteed at all times.

Cable gland M16x1.5

Depending on the connection situation, the cable gland can be inserted in one of the 4 M16 openings. (Tightening torque 5 Nm)

Remove actuator cable:

The connecting cable of the VST damper actuator can be removed from the VRU controller using a screwdriver (size 0...3) as shown in the illustration.







NFC connection Belimo devices marked with the NFC logo can be operated with the Belimo Assistant App.

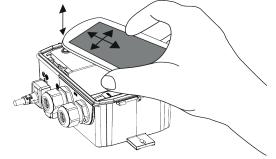
Requirement:

- NFC- or Bluetooth-capable smartphone

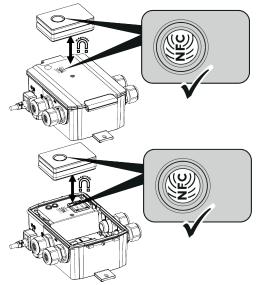
- Belimo Assistant App (Google Play & Apple AppStore)

Align NFC-capable smartphone on the device so that both NFC antennas are superposed.

Connect Bluetooth-enabled smartphone via the Bluetooth-to-NFC Converter ZIP-BT-NFC to the device. Technical data and operation instructions are shown in the ZIP-BT-NFC data sheet.

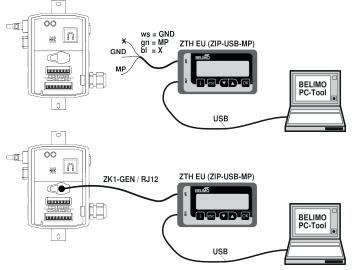


Converter ZIP-BT-NFC



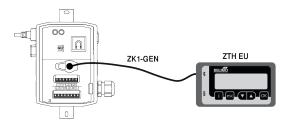
Service Tools connection

The device can be configured by ZTH EU via the service socket or by the Belimo Assistant App via NFC.



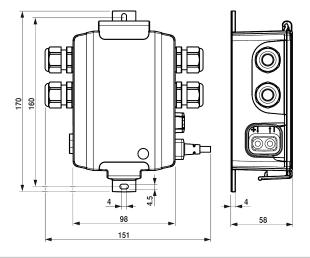






Dimensions

**Dimensional drawings** 



# **Further documentation**

- Data sheets for VST-actuators
- VAV-Universal application description
- Tool connections
- Description Modbus register
- Description Data-Pool Values
- Description Protocol Implementation Conformance Statement PICS
- Introduction to MP-Bus Technology
- Overview MP Cooperation Partners